# Shading and Recognition

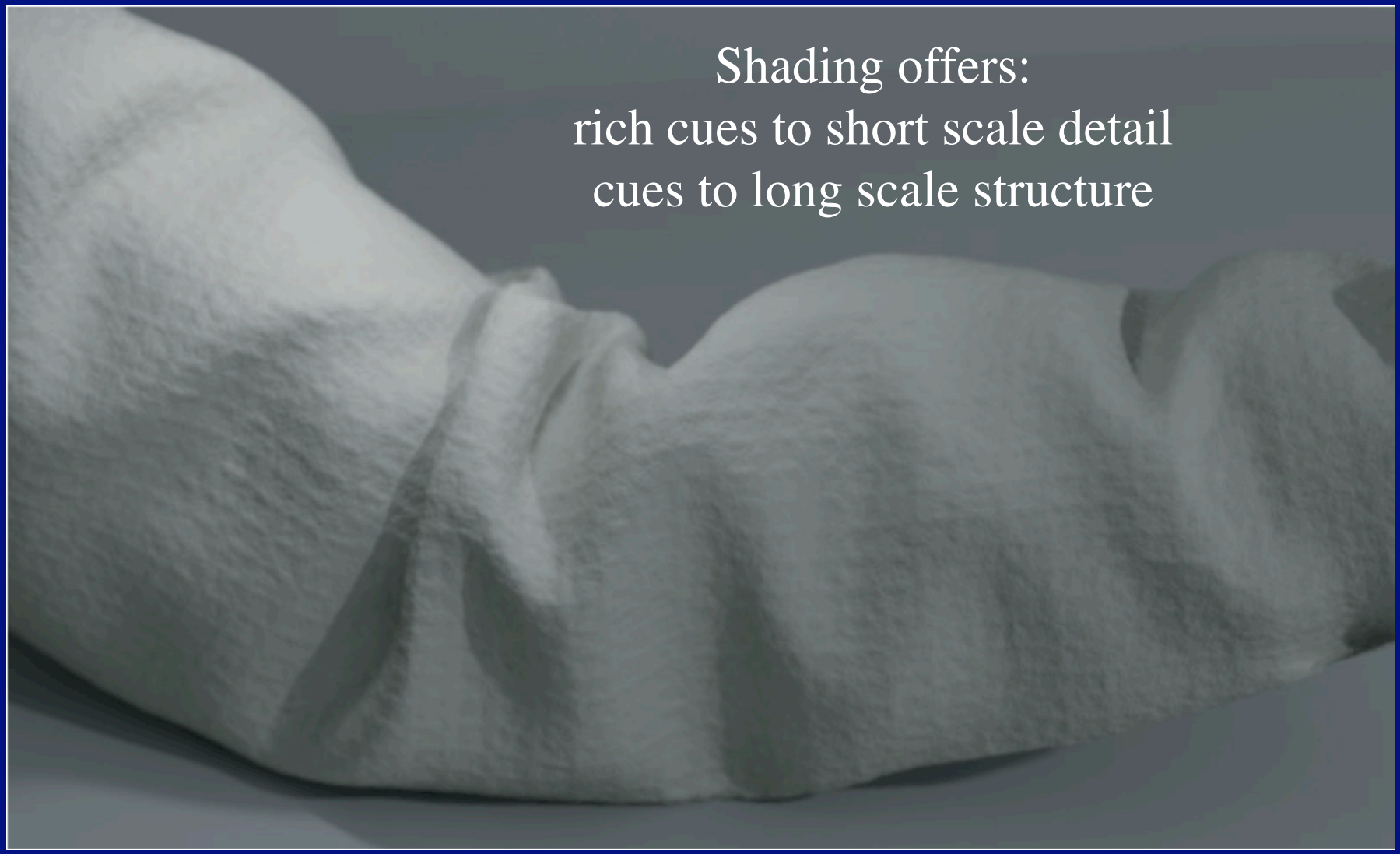
OR

The first Mrs Rochester

D.A. Forsyth, UIUC

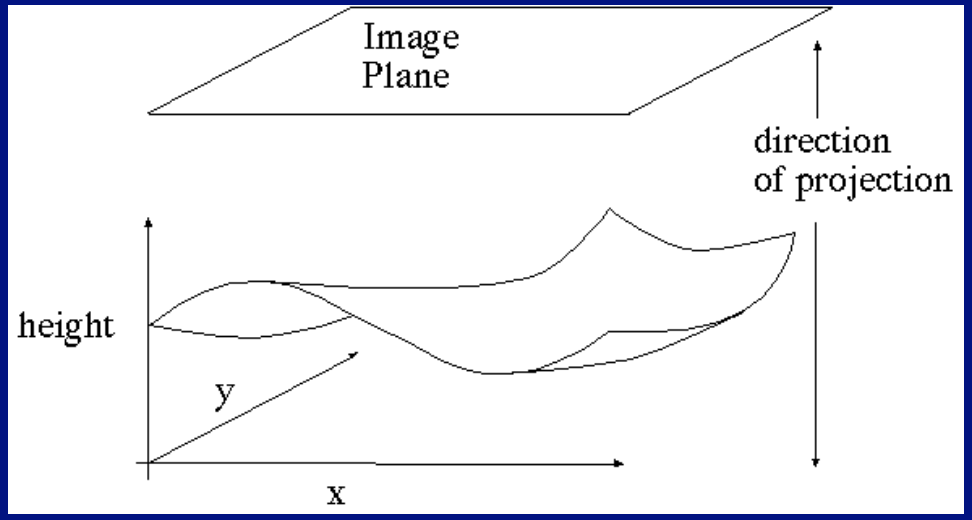
# Structure

- Argument:
  - why shading
  - why shading analysis died
  - reasons for hope
- History
  - Classical SFS+Critiques
  - Primitives
- Reconstructions are possible
  - Variable source shading analysis




From White+Forsyth 07

# Reconstruction from shading




- Conventions:
  - Orthography
    - (but. for example, Prados+Faugeras
  - Height field
    - partial derivatives are written p, q

# Reconstruction from shading

$$R(p, q; \mathbf{S}) = I(x, y)$$

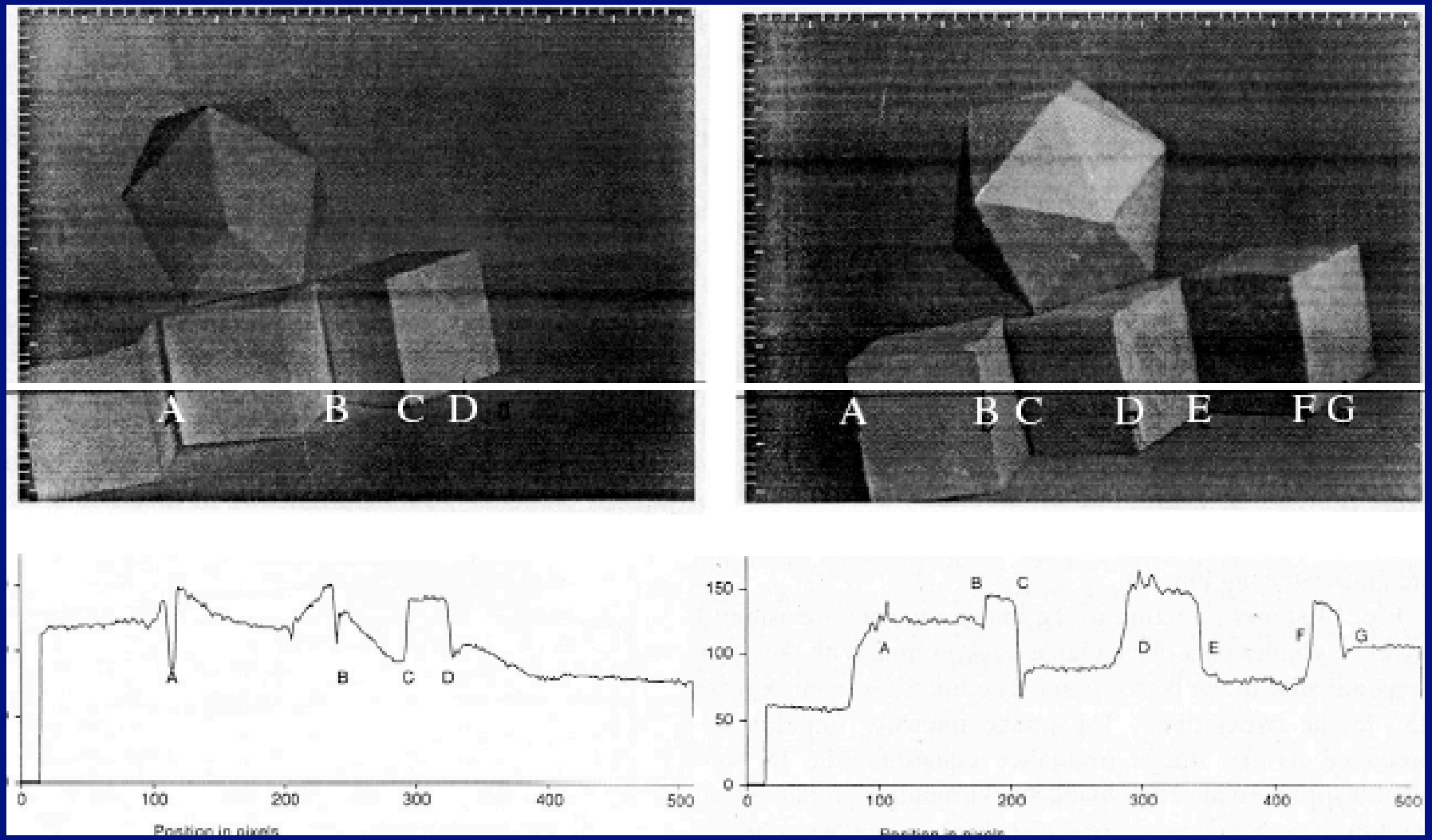
Reflectance Map

Image intensity

- Local model
  - Points with the same normal get the same shading value
- The Image Irradiance Equation (IIE)
  - Horn, 1970 and lots of later papers by lots of authors
- This is a PDE
  - First order, non-linear, actually Hamilton Jacobi

# Physical Critiques

- Real shading is not local
  - interreflections
    - points with the same normal get different shading values
- Devastating
  - because a physically exact formulation is unmanageable
    - (it has been tried, Nayar et al 91)
    - cannot account for distant radiators we can’t see




Forsyth Zisserman ’89, ’91
after Gilchrist, Koenderink, etc.

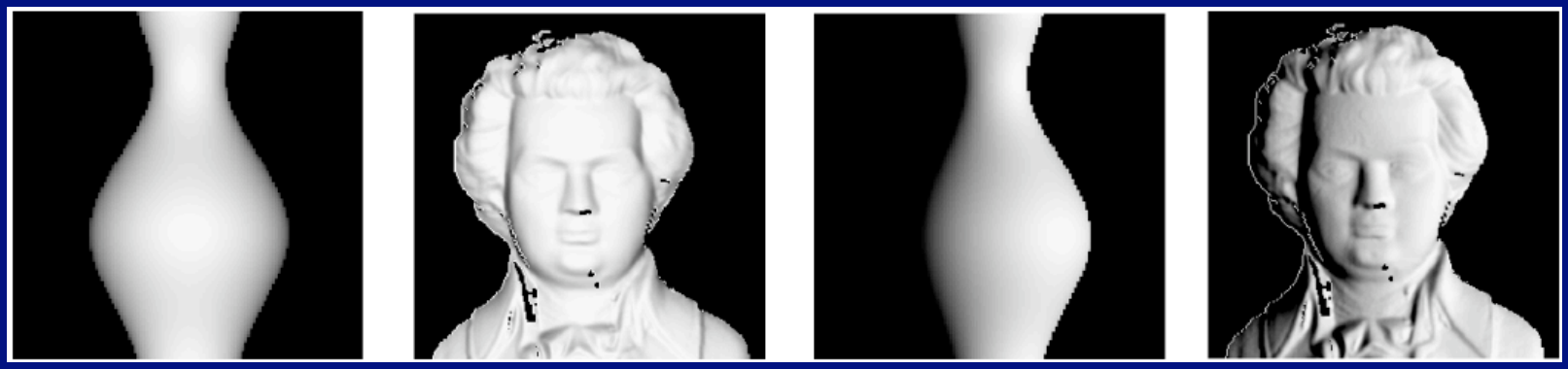
# Existence

- Solutions do not exist for rich boundary conditions
  - current literature says:
    - not a problem - want reconstruction from minimal geometry data
- Options
  - classical fails
  - Lipschitz  (too many solutions)
  - Viscosity  (one, but no physical justification for choice)
    - RouyTourin 92, Lions et al 93, Prados Faugeras 03
- Real world
  - many rich sources of geometric constraint (identity; stereo; SFM;...)
  - should not impede existence

General Guideline:  A formulation which doesn't have existence for natural problem instances needs to be fixed

# Pragmatics

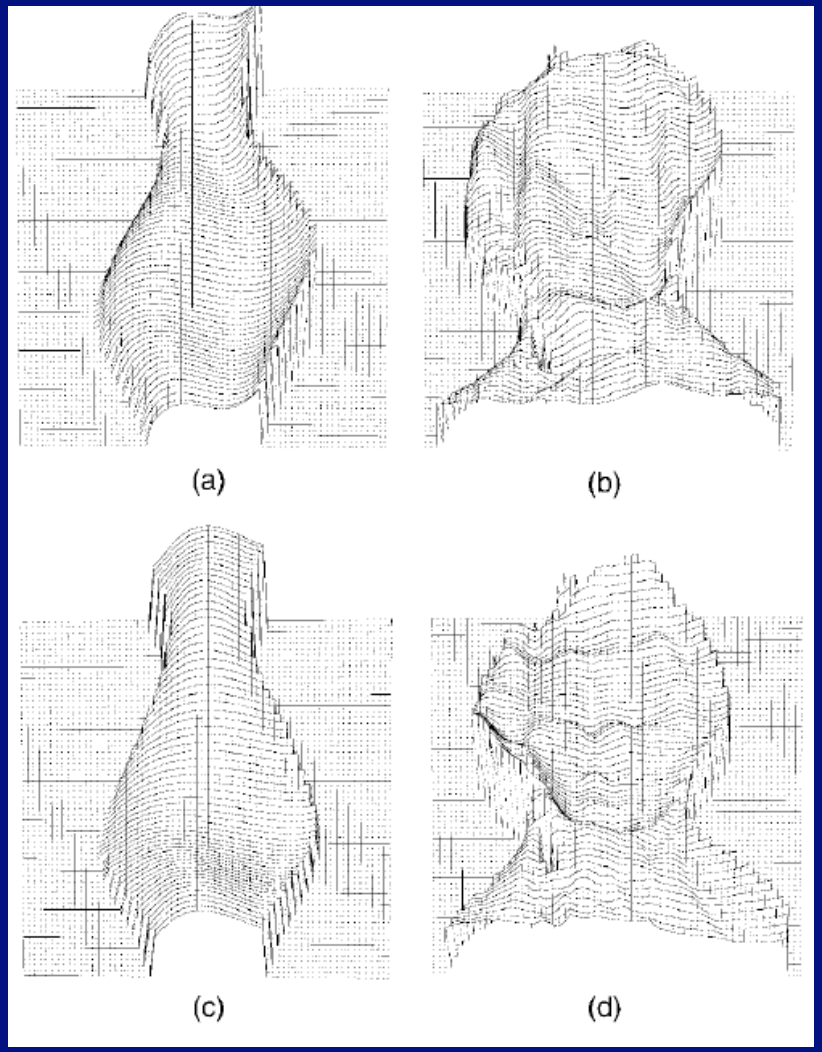
- Shape from shading doesn't work
  - ample evidence
    - No comparison between right answer and reconstructions
    - Poor results on synthetic (!) data

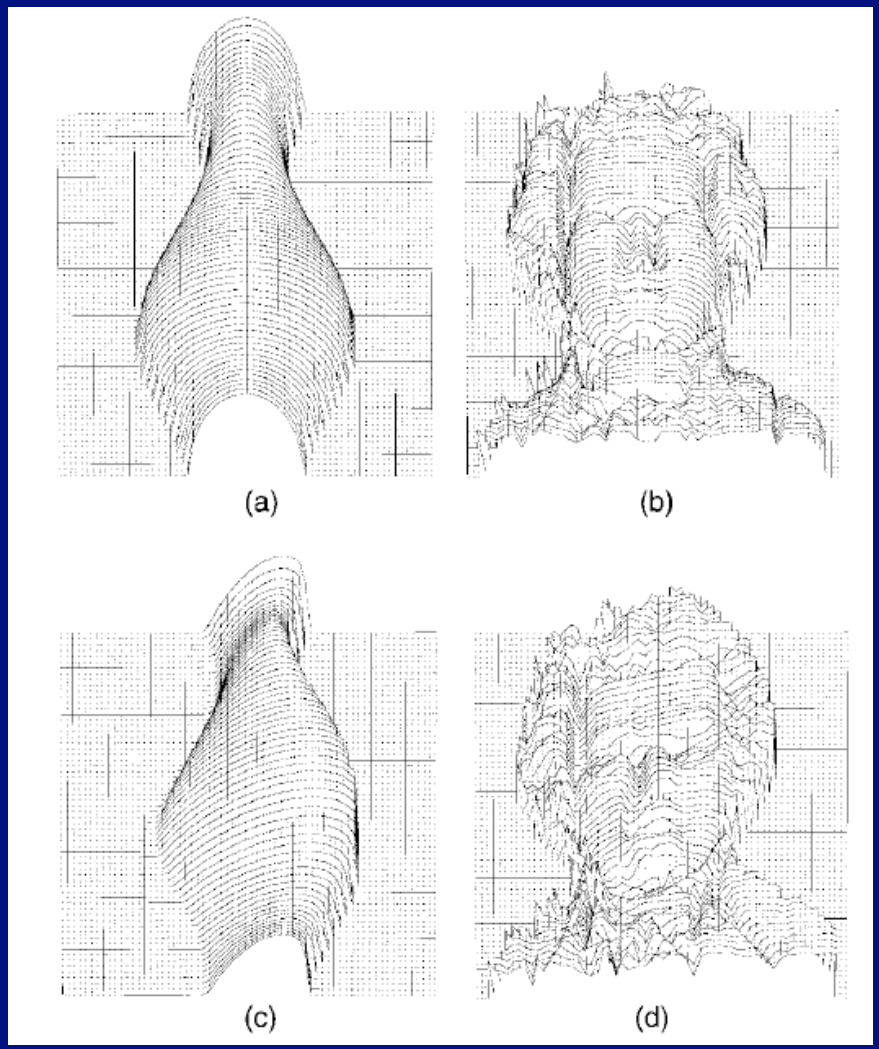


From Zhang ea, 99

# Pragmatics

From Zhang ea, 99



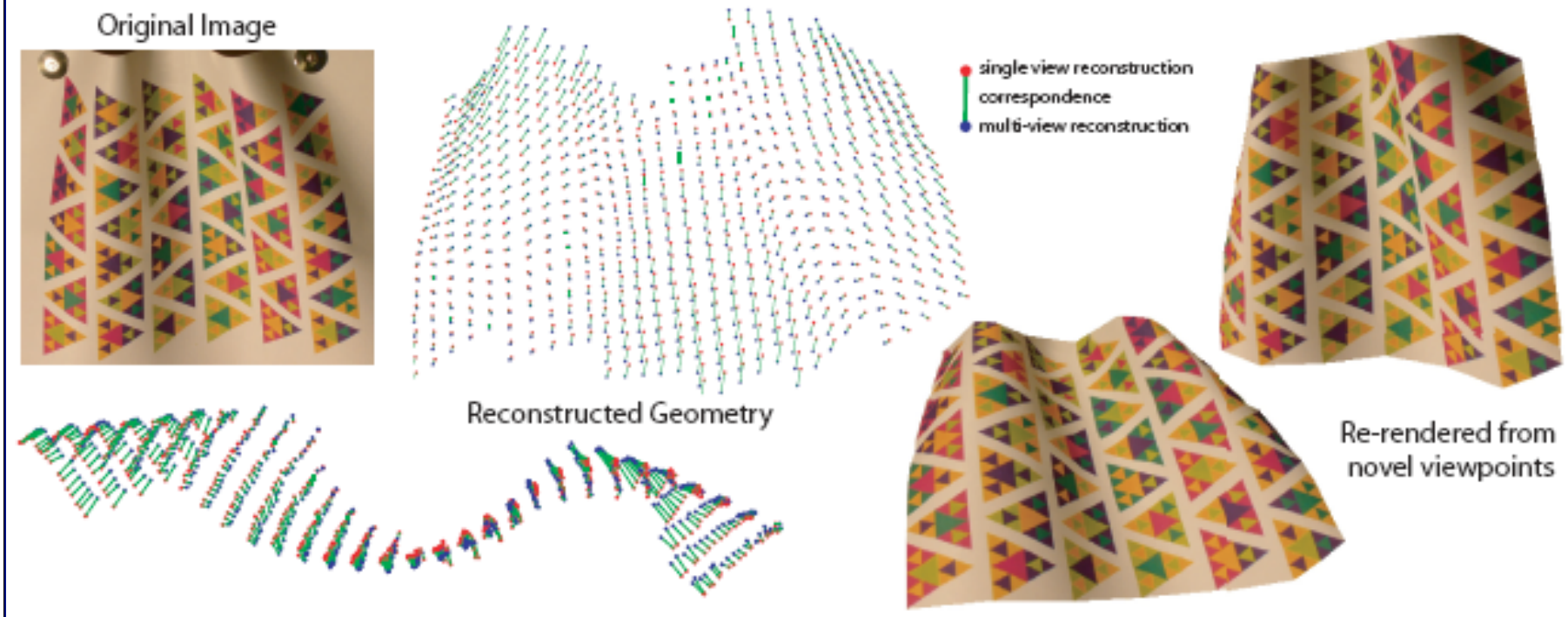
# Minor critiques

- The world isn't ideal diffuse
  - True, but so what - if we can't solve the easiest case...
- There are specularities
  - see above
    - and we can build specularity detectors
- Albedo varies
  - but we have quite good theories of how to infer albedos

# Reasons for hope

- Evidence for pragmatic information in shading
  - SF(T+S)
- Evidence that shading cues are compelling to humans
  - Textureshop
  - Retexturing movies
  - Complex, mixed picture from psychophysics
- Evidence that shading is distinctive
  - Face detectors
  - Some others, rather ragged

# SF(T+S)  Shading disambiguates texture

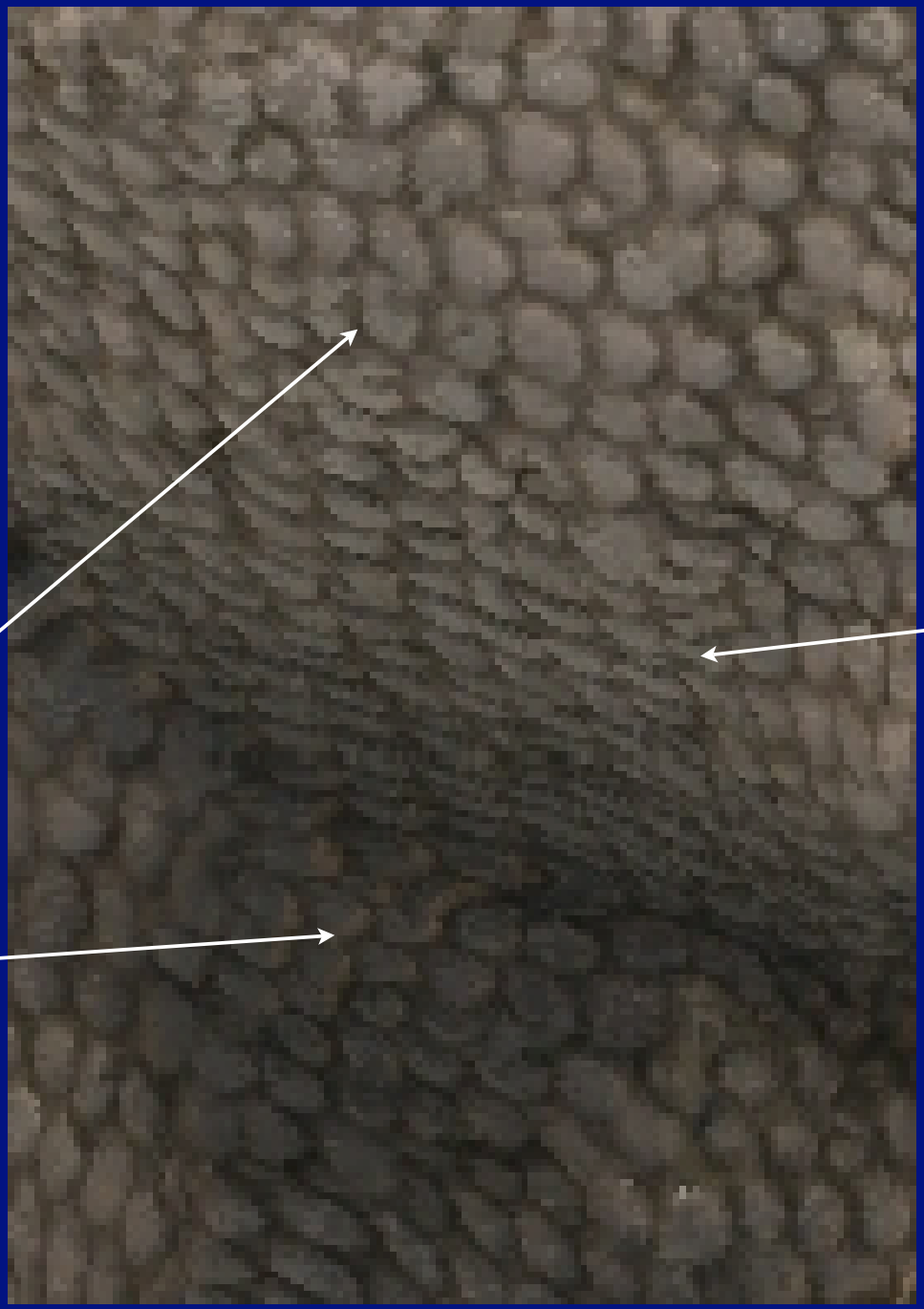



White+Forsyth 06

# Textureshop

- Hart+Fang, 04
- Retexture illuminated surface by:
  - Obtaining normal estimate from local shape from shading
    - normal estimate is largely meaningless
  - Use this to compute texture normal
  - Shade this texture with original illumination estimate
- Interesting because
  - In a cue conflict between texture and shading, texture loses

Fang + Hart 04



# Retexturing movies

- White+Forsyth 06
- Retexture moving surfaces by
  - Building non-parametric estimate of illumination from corners
    - assuming silkscreen, known colors, not known texture
  - Rectify texture to very rough geometric (affine distortion) model
  - Shade with illumination estimate
- Get shading right, it looks natural with weak geometry
  - Shading cues beat motion cues? (at short scales?)
  - Quality issues are
    - flicker
    - surfaces look rigid when fold shading is not reproduced.


Original with Tracking
Retextured Video

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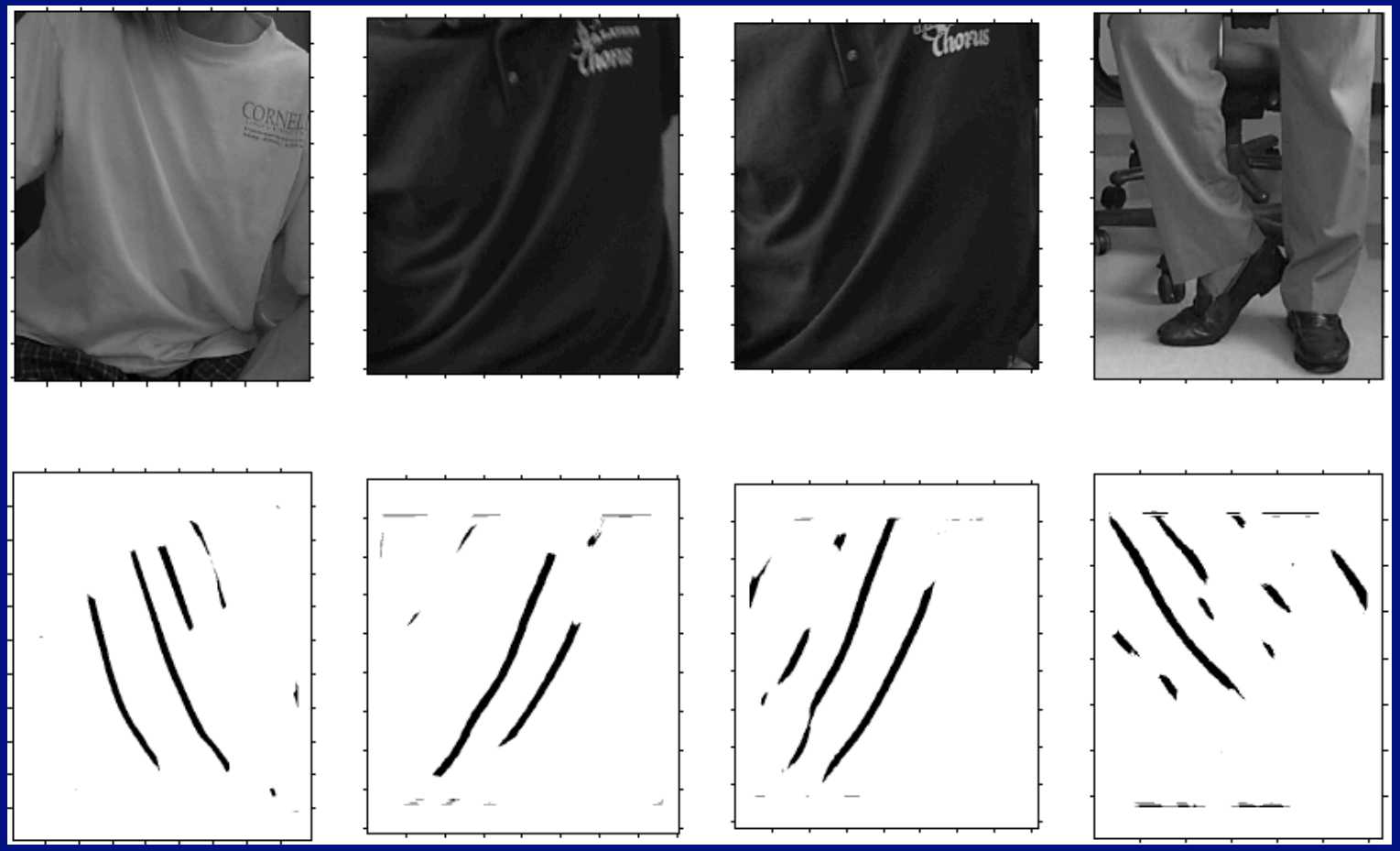
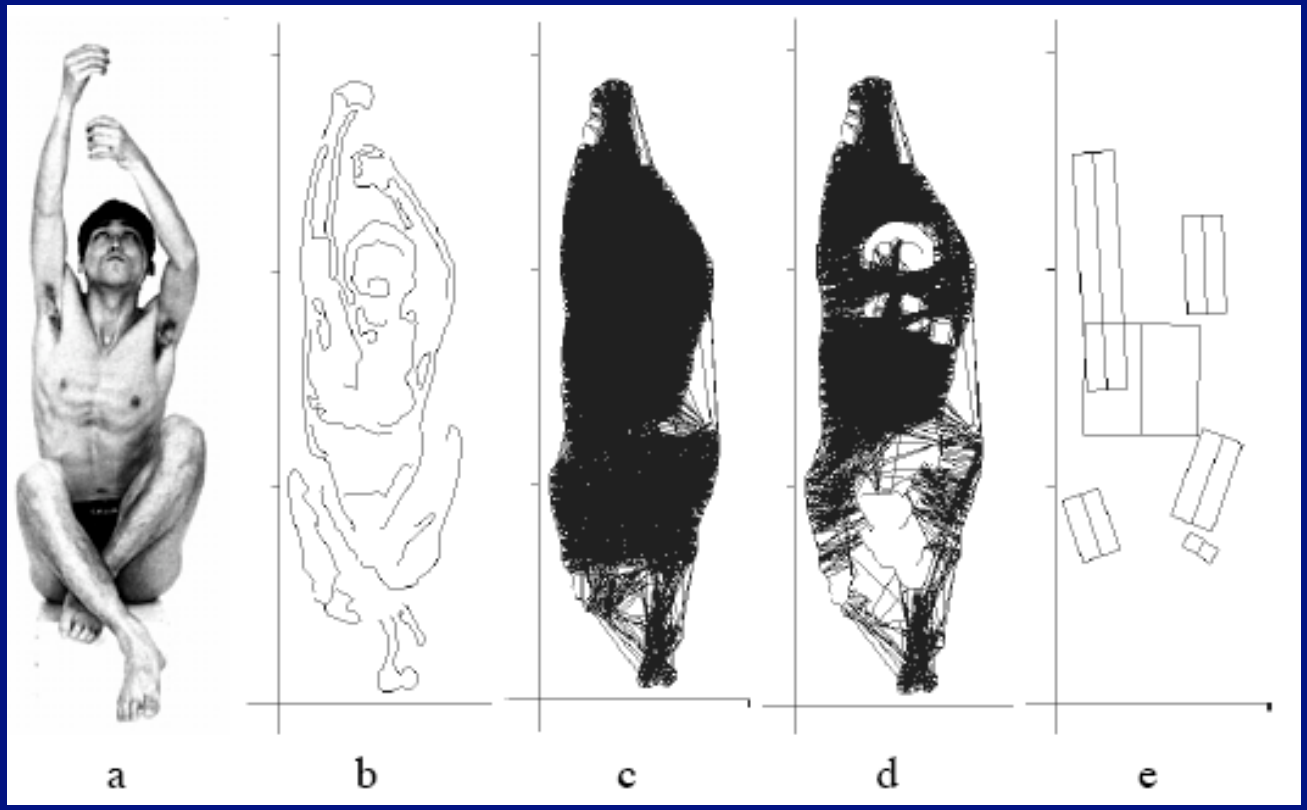
# Shading Primitives

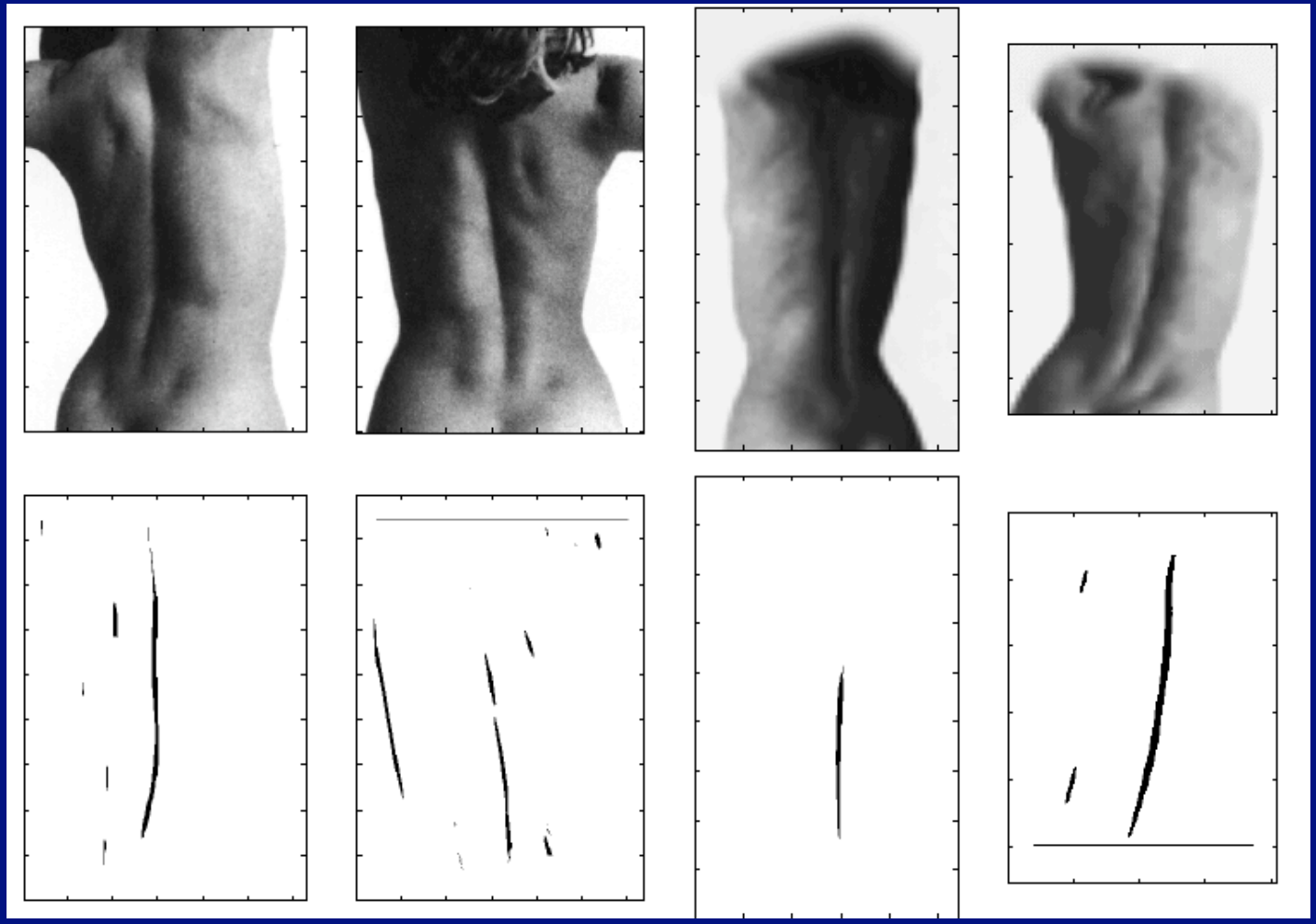
- Shading patterns on certain structures are stylized
  - We might be able to spot such patterns and use them
- Huge success
  - Frontal face detectors
- But...
  - few examples
    - Pits, etc. (Koenderink ’83)
    - Folds, Grooves, Cylinders (HaddonForsyth, 98a, b)
    - Objects in fixed configuration (Belhumeur+Kriegman ’98)
  - hard to deploy in natural ways



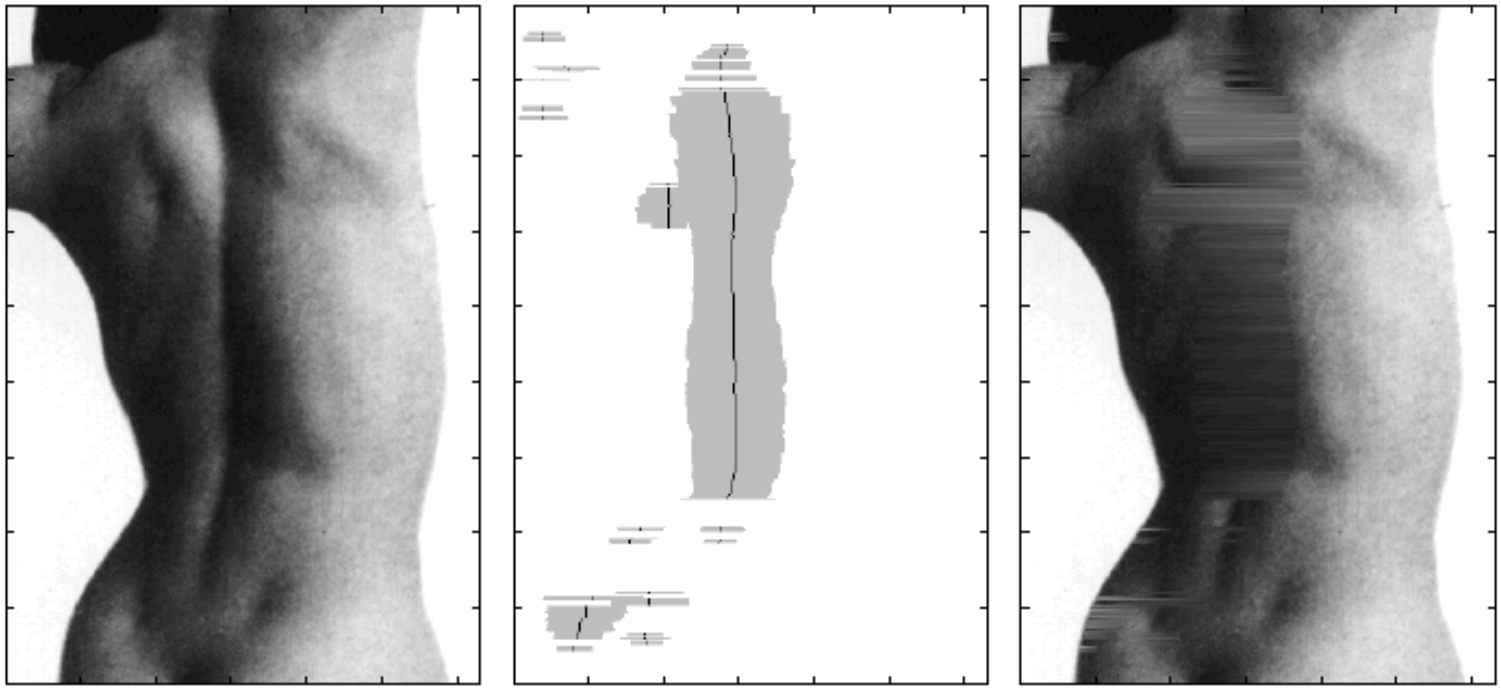
HaddonForsyth 98a



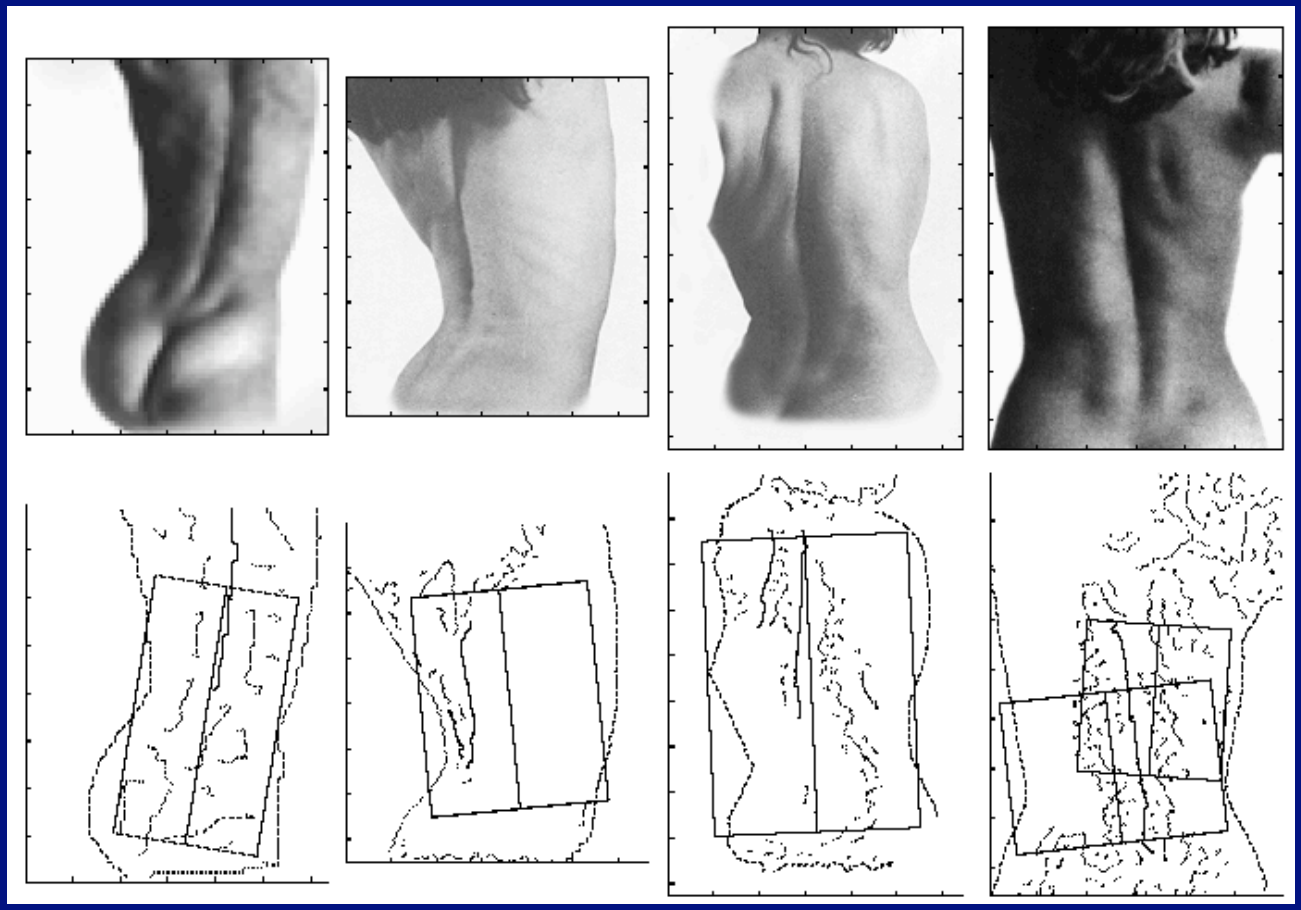

HaddonForsyth 98b



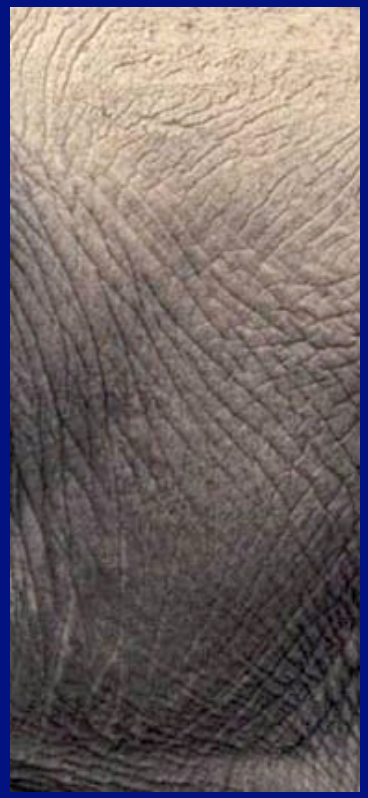
HaddonForsyth 98b

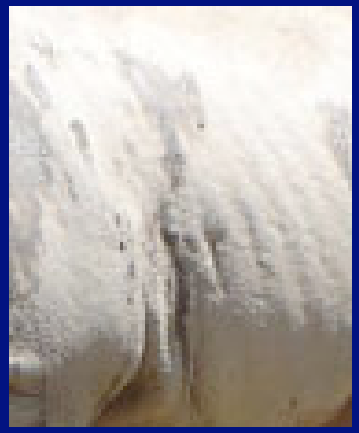
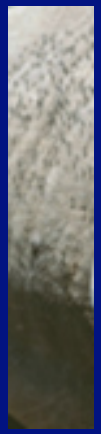
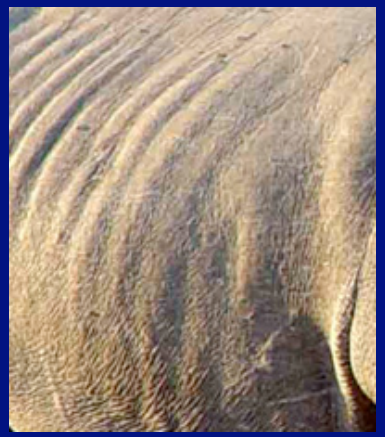


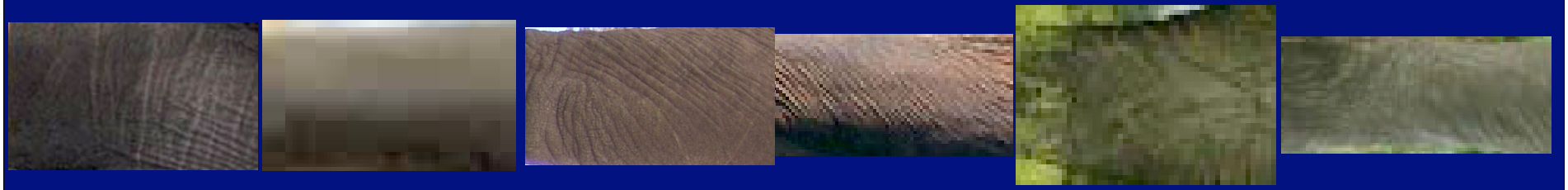
HaddonForsyth 98b



HaddonForsyth 98b



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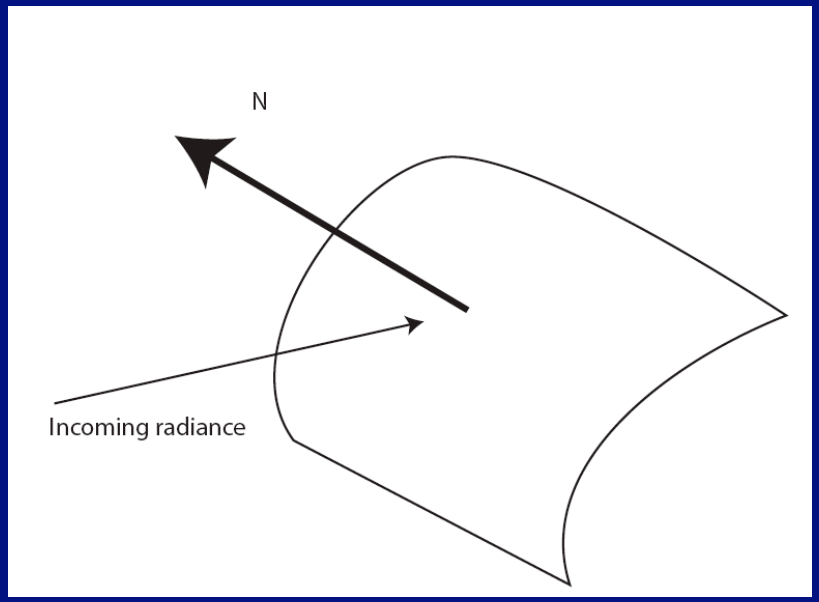
# The Irradiance integral

- Obtain radiosity by
  - summing incoming radiance over all directions



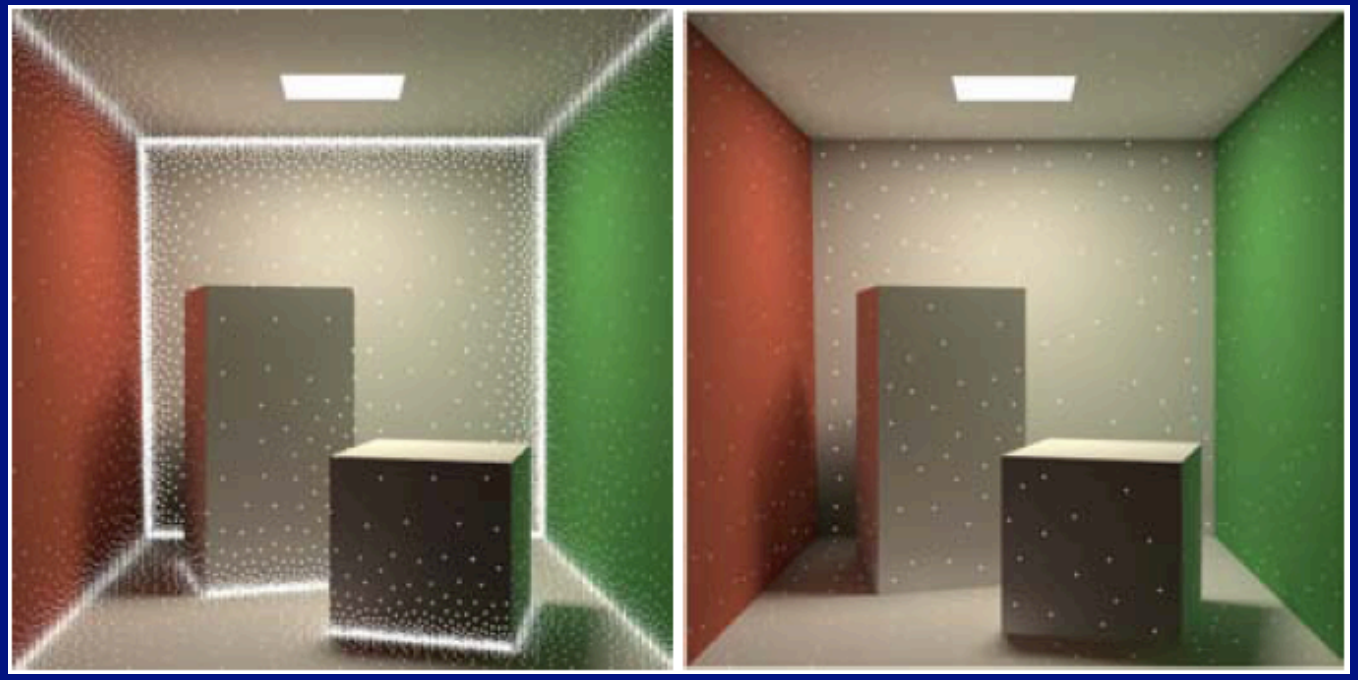

$$B(x,y) = \int_{\Omega} \rho(x,y;\omega_i) L(x,y;\omega_i) \cos\theta_i d\omega_i$$

# The Irradiance Integral

- IIE
  - radiance comes only directly from the luminaire
- Rendering
  - radiance consists of direct term + indirect term
    - indirect term changes slowly over space
      - irradiance cache (Ward, 88, 92)
      - radiance cache  (ArikanForsyth, 04)
  - complex angular patterns of radiance are not resolved
    - (Ramamoorthi Hanrahan, 01)
    - useful in photometric stereo (Basri, Jacobs, Kemelmacher 07)

# Illumination changes slowly over space

Radiance Cache Samples



Irradiance Cache Samples

Figure from Arikan Forsyth 05

# The effective source

$$R(p, q; \mathbf{S}_e(x, y)) = I(x, y)$$

- A spatially varying source
  - that produces the right answer from the reflectance map
- Properties
  - not very different from ideal source
  - difference changes slowly over space

# Variable Source Shading Analysis

Minimize

Slow change in effective source

Effective sources similar to source

$$\theta_1 \sum_{i \in Sources} \int_\Omega \| \nabla \mathbf{S}_e^{(i)}(x,y) \|^2 dA \quad + \quad \theta_2 \sum_{i \in Sources} \int_\Omega \| \mathbf{S}_e^{(i)}(x,y) - \mathbf{S} \|^2 dA +$$

$$\theta_3 \int_\Omega (f_{xx} + f_{yy})^2 dA \quad + \quad \theta_4 (\int_\Omega dA_s - A_0)^2$$

No free creases

Extra area is expensive

Subject to:

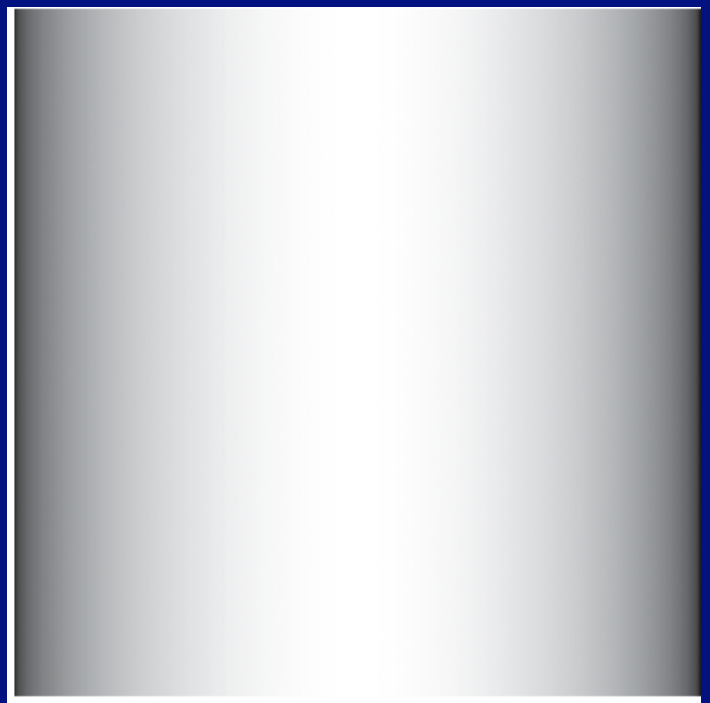
$$R(p, q; \mathbf{S}_e^{(i)}(x,y)) = I(x,y)$$

Boundary conditions

# Variable source shading analysis

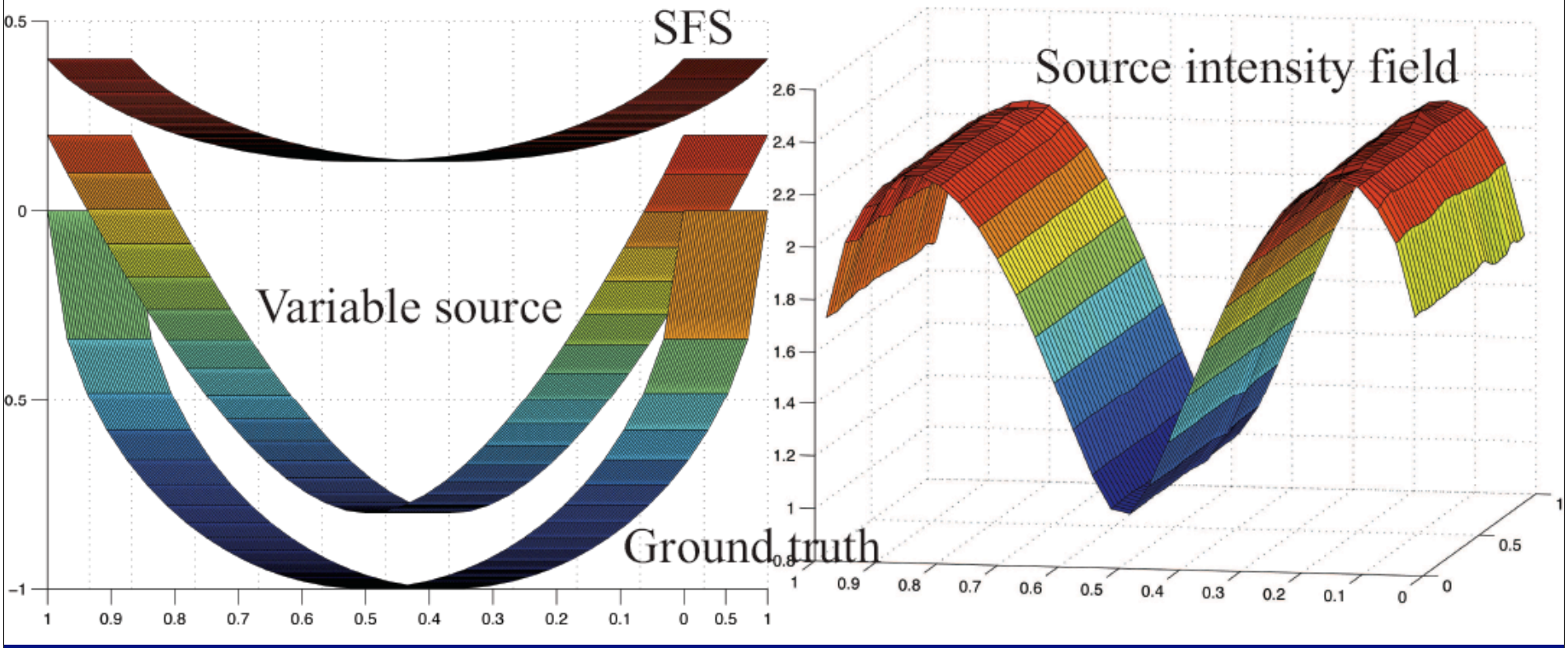
- Solution always exists
  - if boundary conditions are consistent
- Arbitrary (consistent) boundary conditions OK
- Can do 0, 1, 2.... sources
- Area regularizer is very helpful
- Somewhat stabler problem if we substitute:

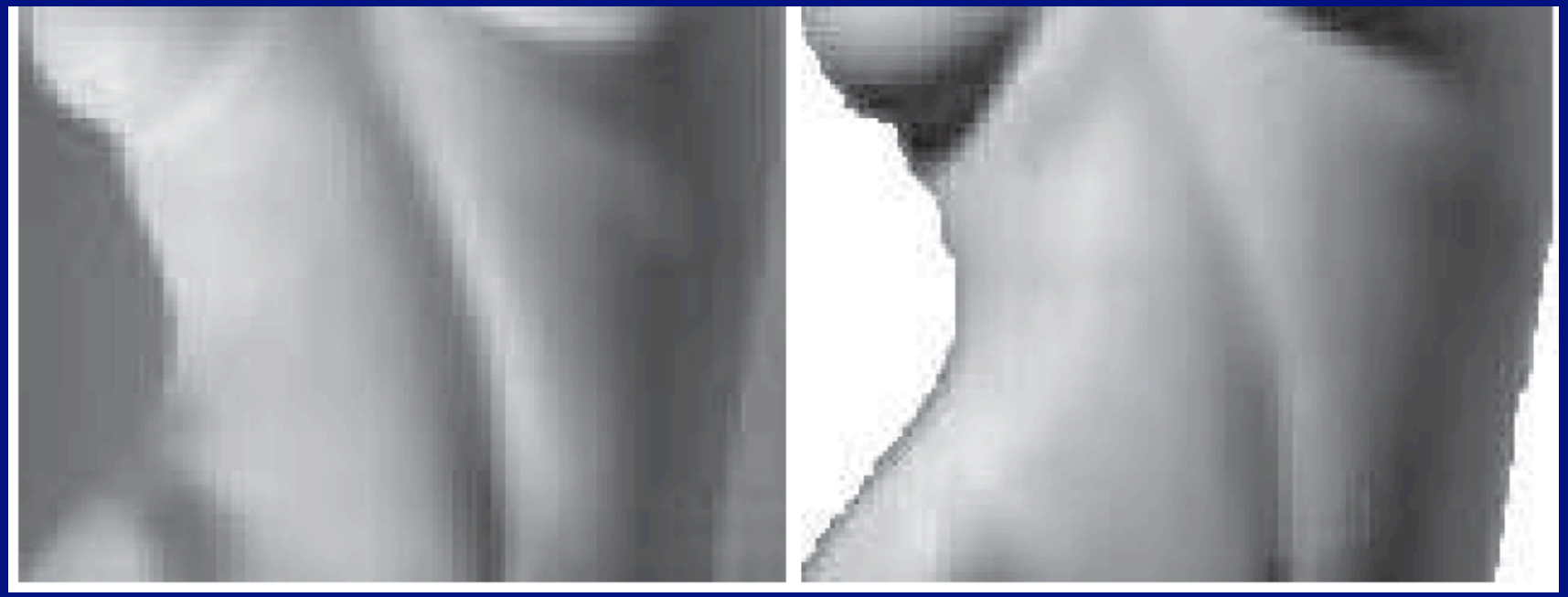
$$\mathbf{S}_e^{(i)}(x,y) = g_i(x,y)\mathbf{S}^{(i)}$$



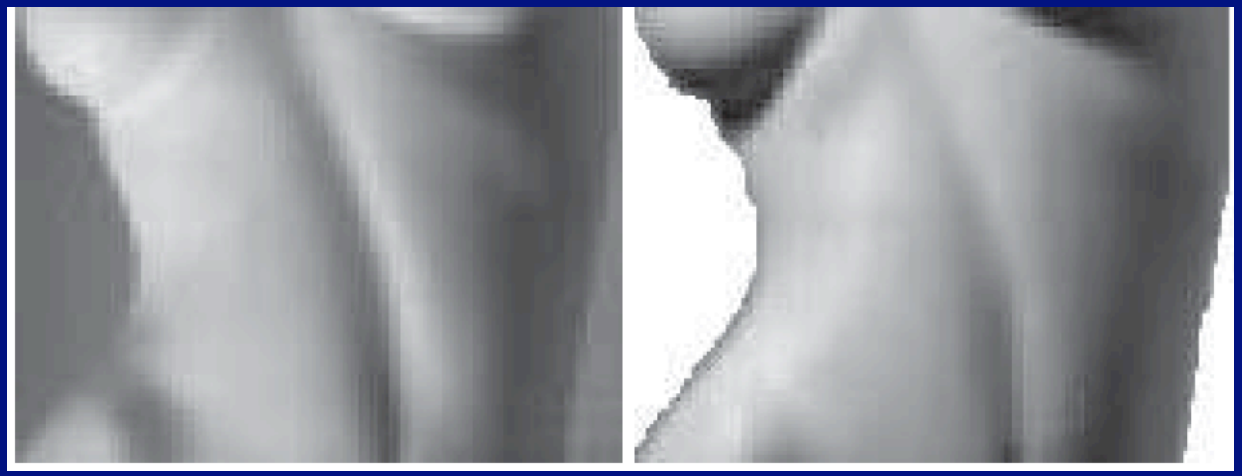
Local shading model

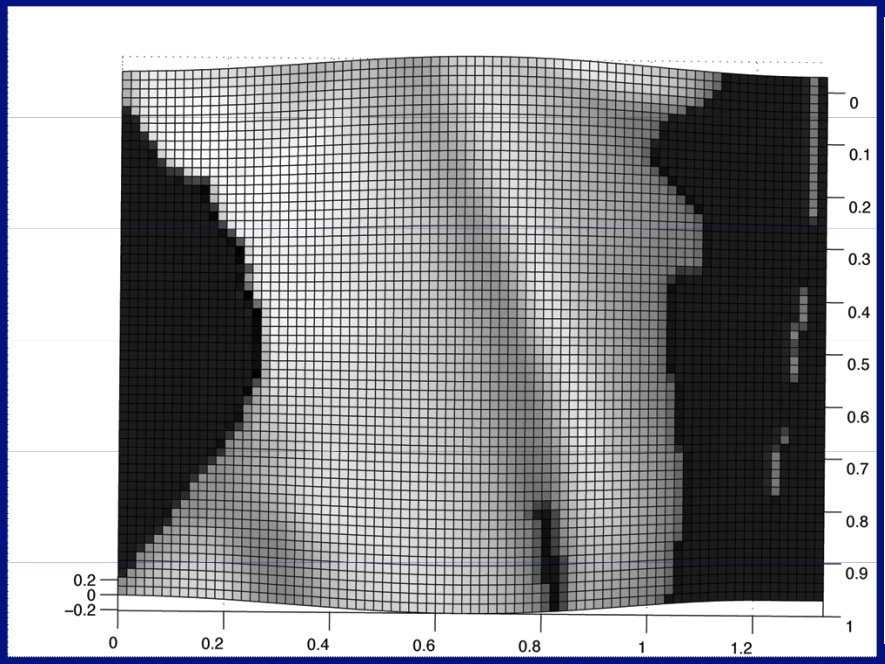
Physically realistic shading

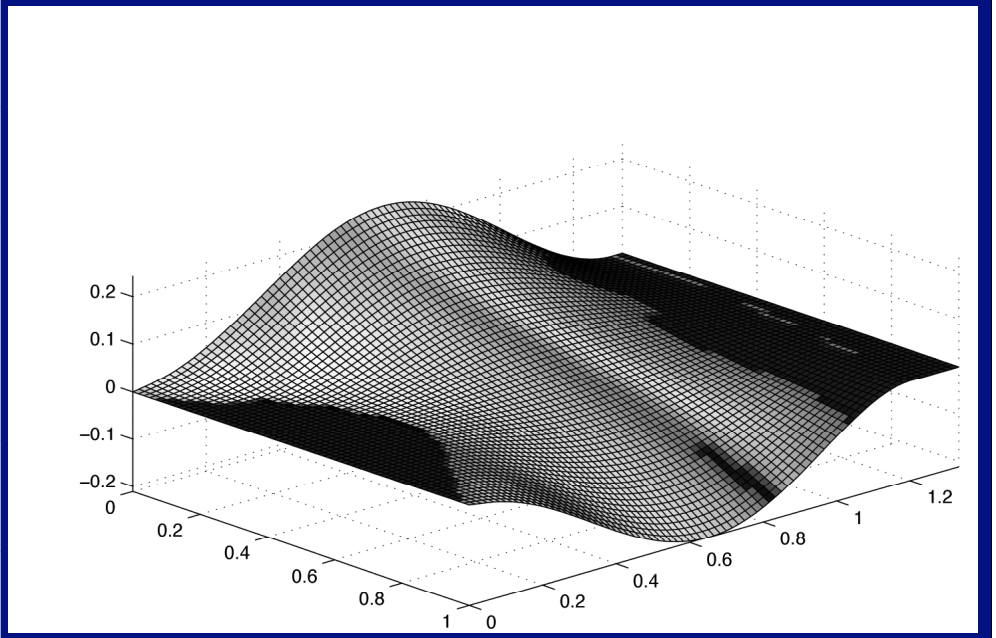

SFS
Variable source
Ground truth
Source intensity field
0.5
0
0.5
−1
1 0.9 0.8 0.7 0.6 0.5 0.4 0.3 0.2 0.1 0 0.5 1
2.6
2.4
2.2
2
1.8
1.6
1.4
1.2
1
0.8
1 0.9 0.8 0.7 0.6 0.5 0.4 0.3 0.2 0.1 0
0
0.5
1



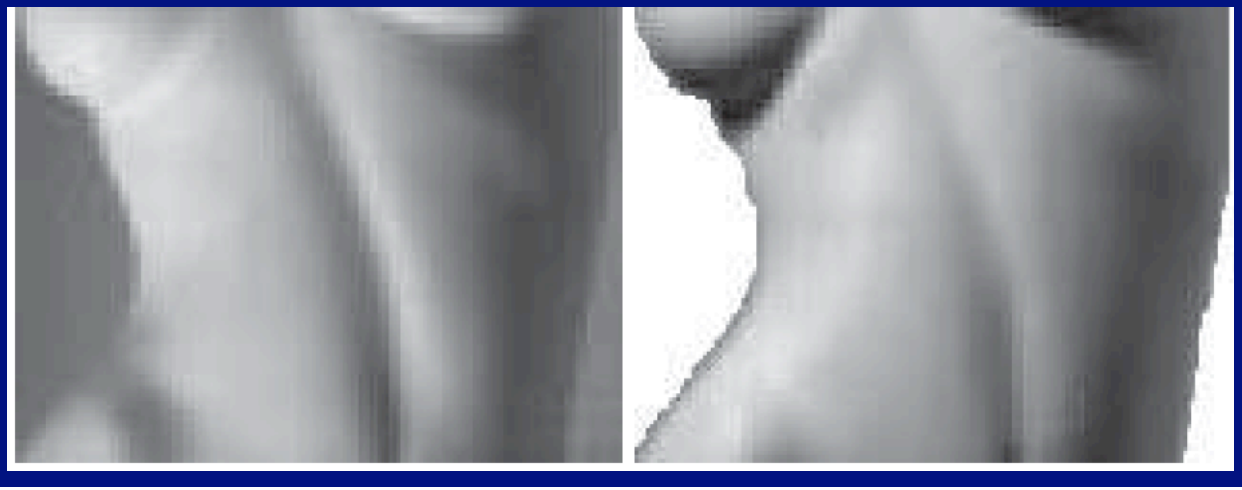
Figures 1a, b of  Koenderink, “Pictorial Relief”, 98

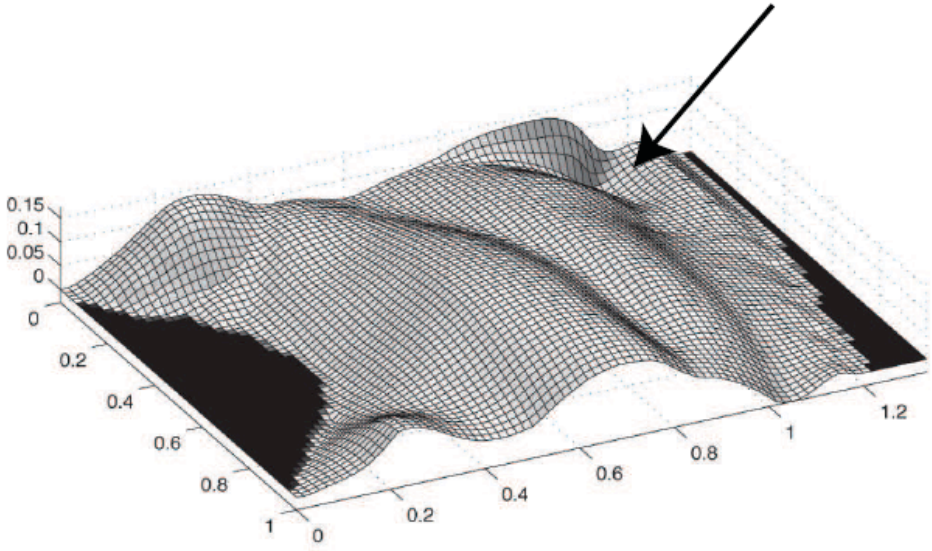




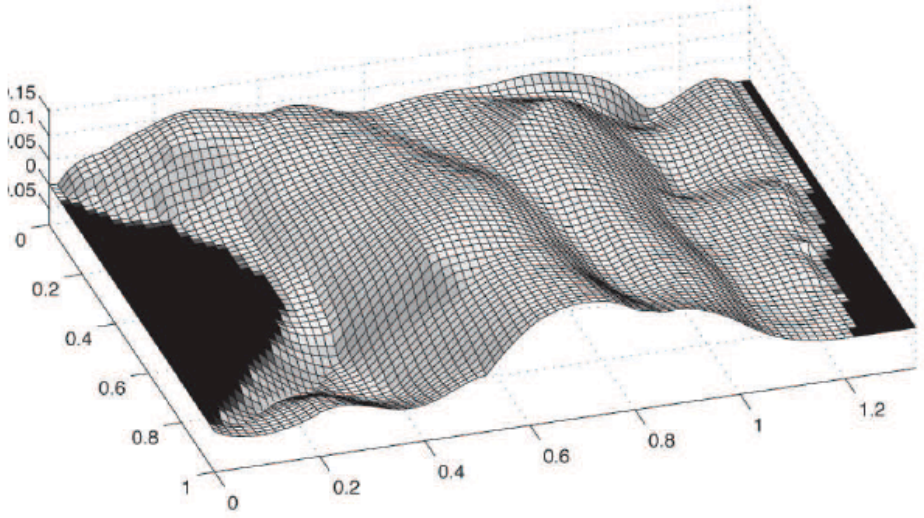




No shading (this isn't unique, but gives some idea of what bc's do)



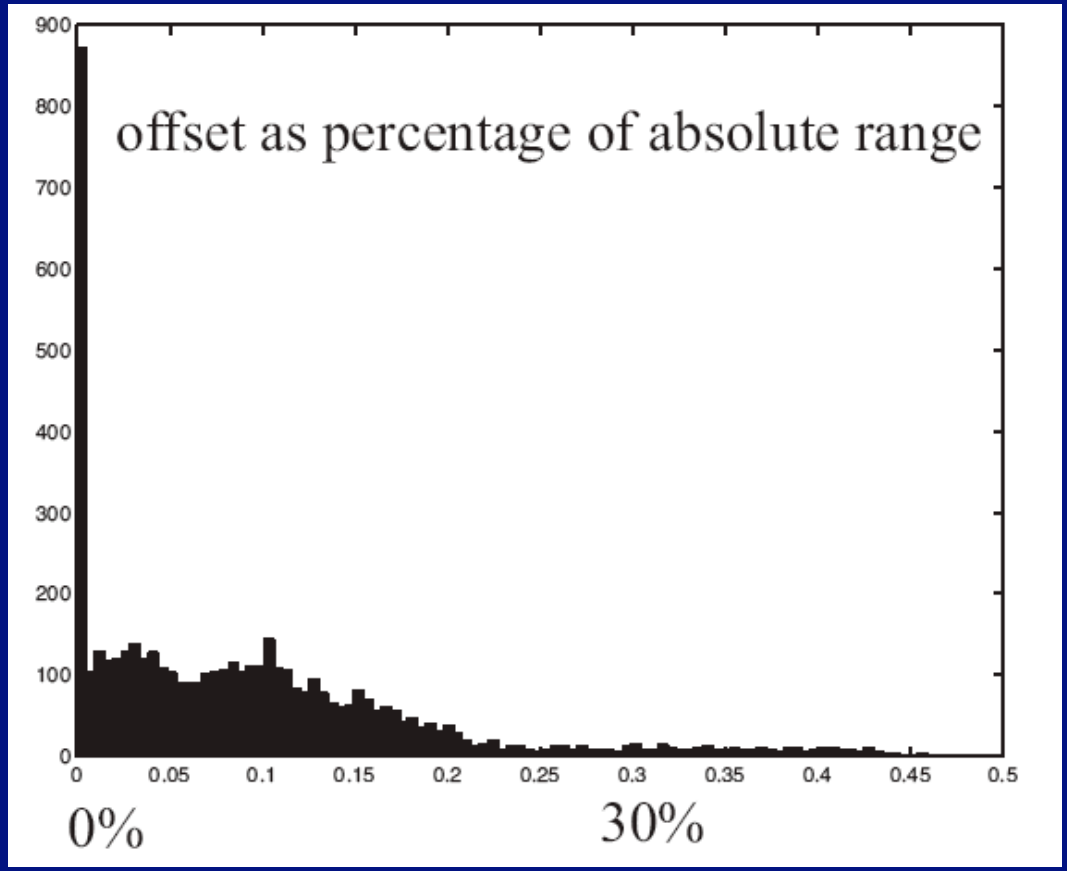



2 Source reconstruction




1 Source reconstruction

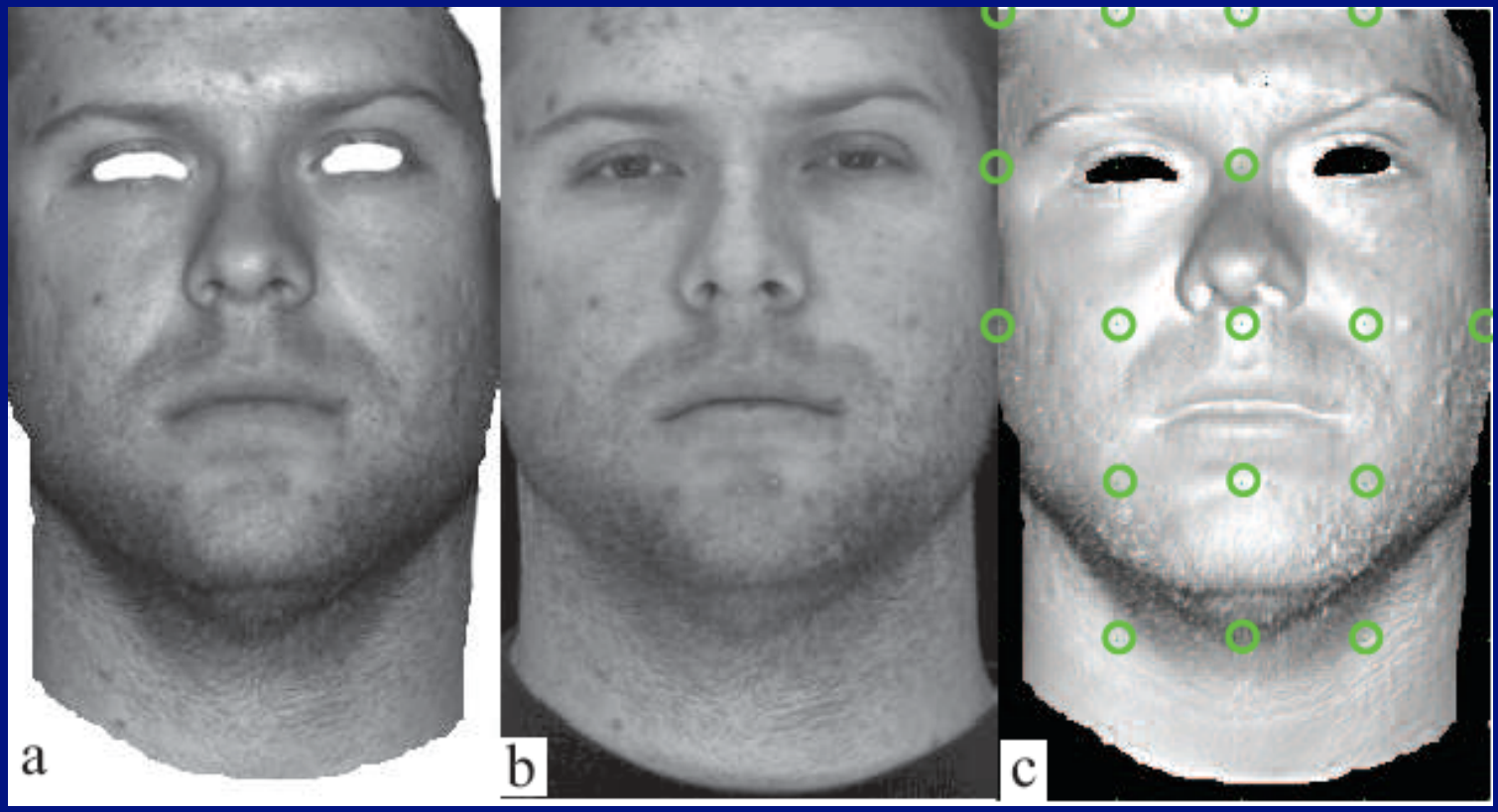
# 1-Source vs 2 Sources

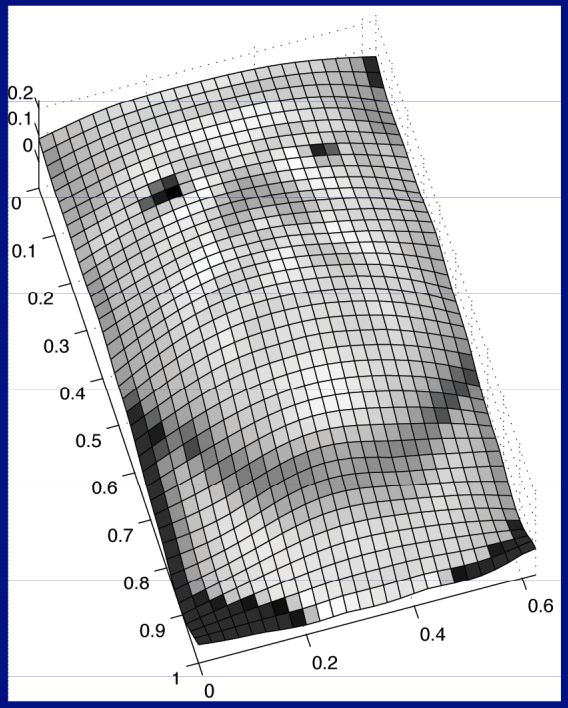


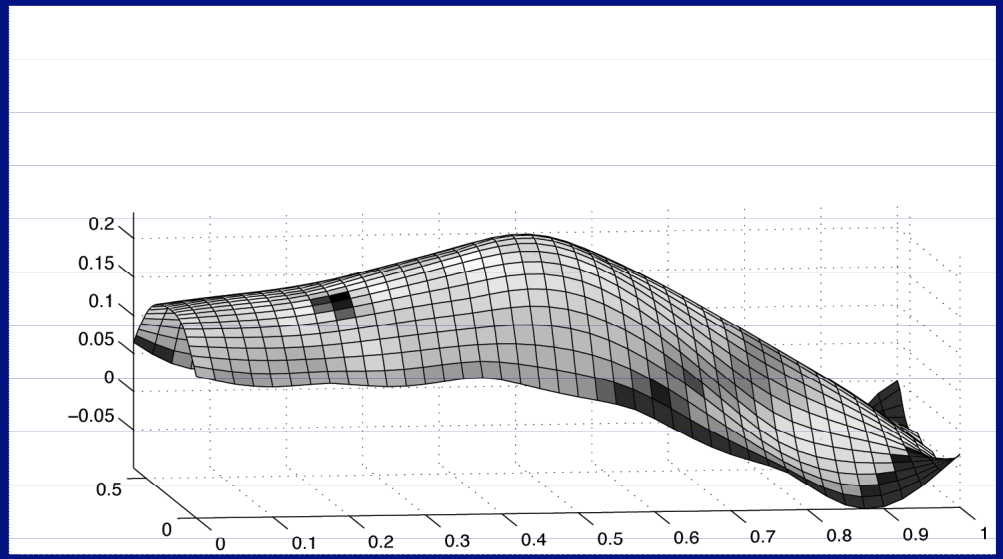
Masked image

Albedo
(inferred from photometric stereo and provided)

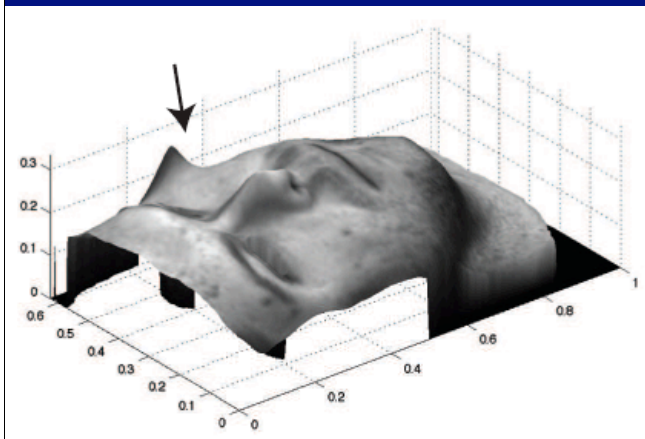
Shading image



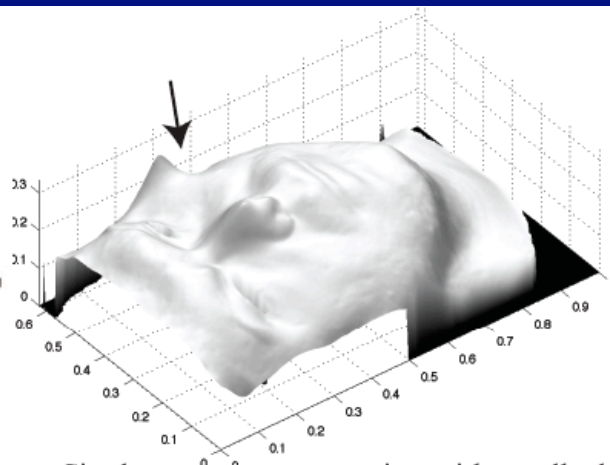


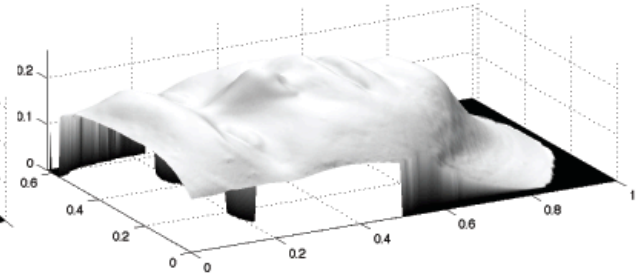

Without shading



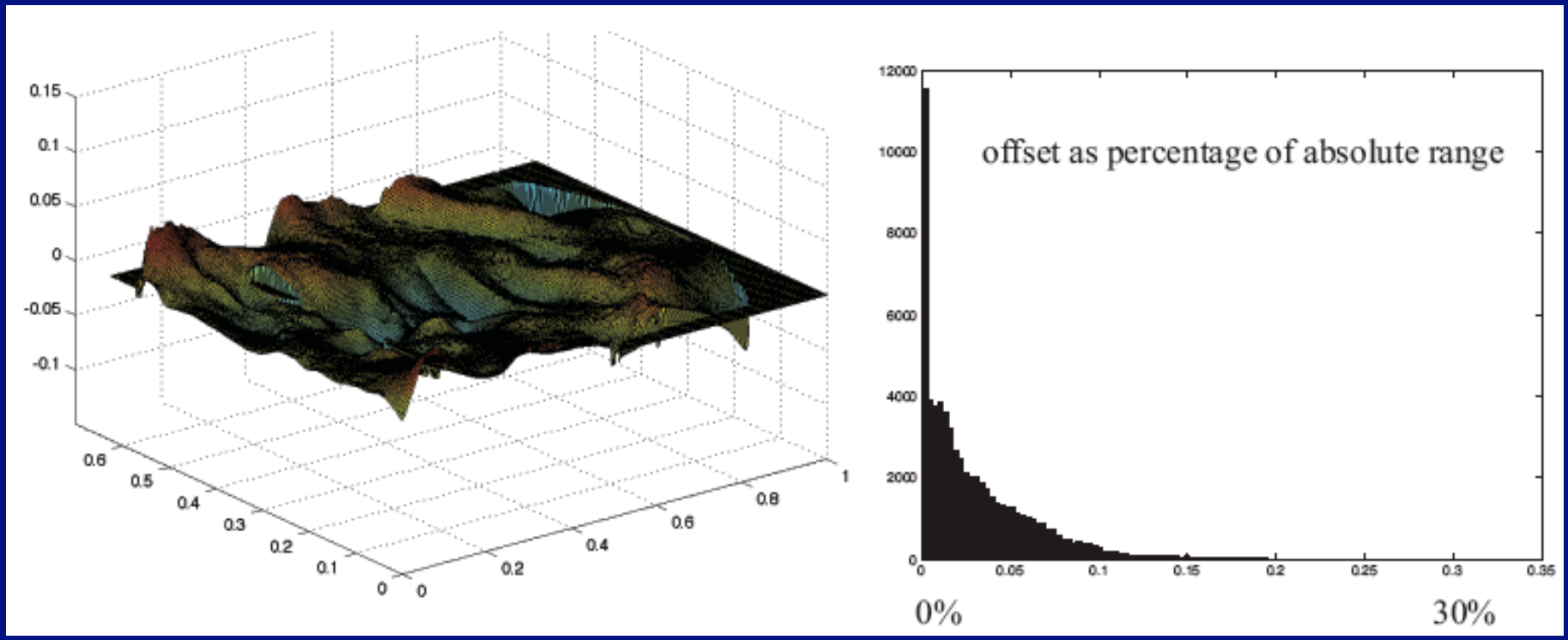

Single source reconstruction with albedo



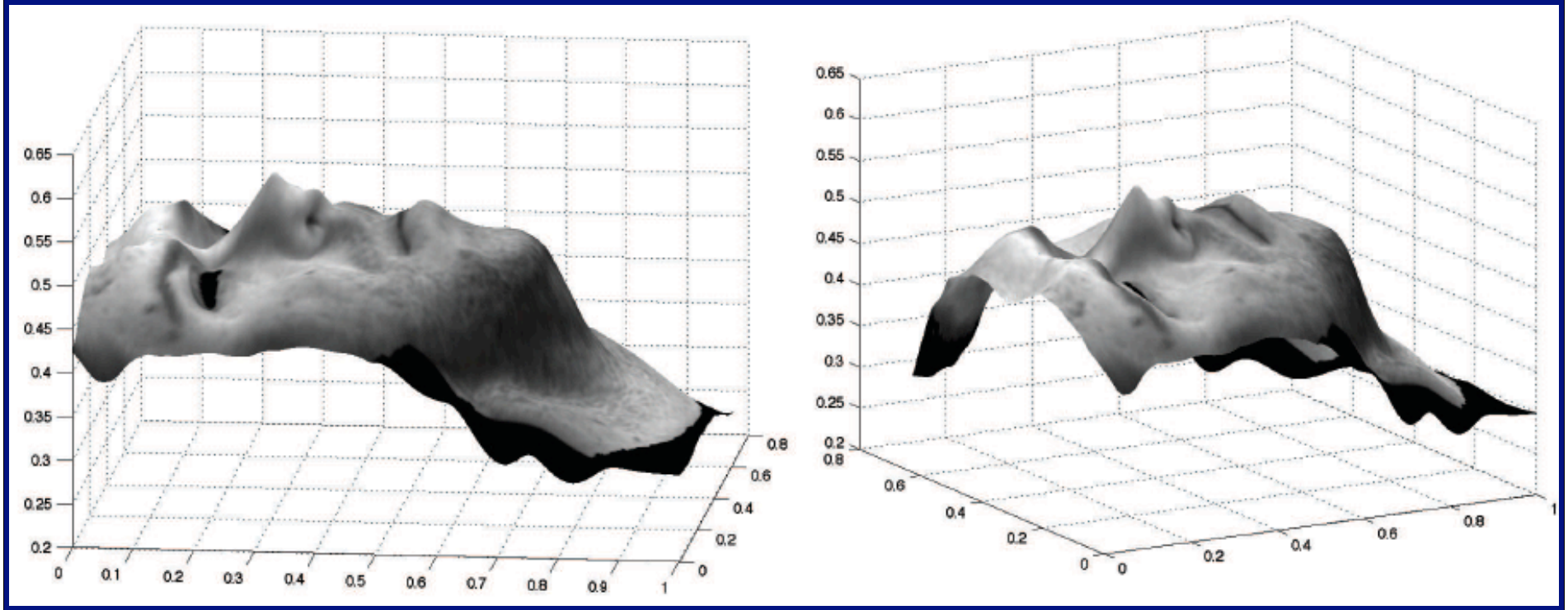

Single source reconstruction without albedo




Reference photometric stereo reconstruction




Single source face against reference photometric stereo reconstruction




320x200 representation:
single source
256000 variables
640 depth constraints (32x20 grid) some masked
Note bump on nose - specularity

# Important points

- There are features which exist over spatial domains
  - at object length scales
- Usable notion of primitive essential
  - to handle unknown objects
- The visual world is very rich
  - cue opportunism is essential for both reconstruction and recognition