

## ALMM DD-ADMM for MRFs.

①

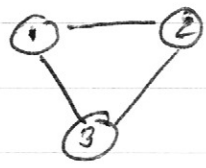
"recall" we could write

$$\text{MAP solu} = \operatorname{argmax}_{(\mu, \nu) \in M(\mathcal{G})} \sum_i \theta_i \mu_i + \sum_a \phi_a \nu_a$$

Why:

- $\mu_i$  are 0-1 variables for each value of each assignment for each unary var - might be vectors
- $\nu_a$  are 0-1 vectors for each n-ary factor
- The hard stuff is in  $(\mu, \nu) \in M(\mathcal{G})$

eg.



- $x_1 \in \{a, b, c\}$
- $x_2 \in \{d, e, f\}$
- $x_3 \in \{g, h, i\}$

so  $\mu_i$  ~~with~~ could be  $(1, 0, 0)$ ,  $(0, 1, 0)$ ,  $(0, 0, 1)$ ,  
 etc  $\theta_i = (c_i(a), c_i(b), c_i(c))$

$v_i$  for 1-2 edge, say,

then  $v_i$  is a 9-D vector, with  
 a single 1 in it

$$\phi_i = (c_{12}(a, d) \dots \dots \dots) \text{ etc}$$

Notice that only some

$\mu_i$ ,  $v_i$  are compatible

eg. we can't have

$$\mu_1 = (1, 0, 0), \mu_2 = (0, 1, 0)$$

$$\phi_1 = (0, 1, 0 \dots \dots)$$

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Construct

$$\text{conv}(\{\text{all compatible } \mu, \nu\}'s)$$

Marginal polytope

Problem: no concise rep'n available  
in most cases.

Relax to Local polytope

$$L(G) = \left\{ (\mu, \nu) \mid \begin{array}{l} \mathbf{1}^T \mu = 1 \\ \nu_\alpha \geq 0 \\ \mu_i \geq 0 \end{array} \right\}$$

only one label

no negative terms in  $\gamma_\alpha$

$\rightarrow H_{i\alpha} \nu_\alpha = \mu_i$

consistency

$$H_{i\alpha} (x_i, x_\alpha) = 1 \quad \text{if} \\ [x_\alpha]_i = x_i$$

④

The consistency term allows us to think of  $\mu, \nu$  as ~~form~~ a probability distribution

(Scaling)

$$\forall \alpha \quad \nu_\alpha = \mu_i$$

ensures that the marginals of the factor terms are consistent w/ the  $\mu_i$

Then we could relax to

$$\max \sum_i \theta_i \mu_i + \sum_a \phi_a^\top \nu_a$$

$$\text{st } \mu, \nu \in \mathcal{L}(\mathcal{G})$$

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In this notation, we introduce one

copy of vars for each factor

$a \leftarrow$  factor  
 $v_i \leftarrow$  var

then require they agree

$$\max_a \sum_a \left[ \sum_i \frac{1}{d_i} (\theta_i^\top v_i^a) + \phi_a^\top v_a \right]$$

$d_i$  degree of  $i$ th node.

$$\text{st. } (v_i^a, v_a) \in M(G_a)$$

$v_i^a = \mu_i$  the elements of factor  $a$

$\rightarrow$  then Jo Dual decomposition.

or ADMM

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Notice that

$$(v_i^x, v) \in M(G_x)$$

means we are working w/ the local polytope. This is because

$$\{(\mu, v) \mid (\mu_{N(a)}, v_a) \in M(G_a)\}$$

↑  
The  $\mu$ 's that appear in factor  $a$

is the local polytope

[ Local constraints imposed only on each factor ]

(6a)

Augmented Lagrangian

$$A_p(\mu, \nu, \lambda)$$

$$= \sum_{a \in \text{factors}} \left[ \sum_{i \in N(a)} \left[ \frac{1}{d_i} \theta_i + \lambda_i^a \right]^T \nu_i^a + \phi_\alpha^T \nu_\alpha \right]$$

$$- \sum_{a \in \text{factors}} \sum_{i \in N(a)} \lambda_i^{aT} \mu_i$$

$$- \frac{\rho}{2} \sum_a \sum_i \|\nu_i^a - \mu_i\|^2$$

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Now we do ADMM.

$$v^{k+1} = \underset{v}{\operatorname{argmax}} A_p(\mu^k, v, \lambda^k) \quad \leftarrow \text{one per factor}$$

$$\mu^{k+1} = \underset{\mu}{\operatorname{argmax}} A_p(\mu, v^{k+1}, \lambda^k)$$

$$\lambda^{k+1} = \lambda^k - \left\{ \text{usual update} \right\}$$



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## Notice

$$\mu^{(k+1)} = \operatorname{argmax} A_\rho(\mu, \nu, \lambda) \quad \text{can be}$$

solved in closed form.

[ Quadratic form ~~of linear constraints~~ ]

The slaves are interesting.

$$\min_{(\nu_{N(a)}^a, \nu_a) \in M(G_a)} \frac{\rho}{2} \sum_{i \in N(a)} \left\| \nu_i^a - \frac{\omega_i^a}{\rho} \right\|^2 - \phi_a^\top \nu_a$$

↑  
cooked up out of  $\mu, \lambda$

Variety of cases:

• Factors are always 2 (MRF)

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rewrite problem as:

$$\min \frac{1}{2} \left[ (z_1 - c_1)^2 + (z_2 - c_2)^2 \right] - c_{12} z_{12}$$

$$\text{st. } z_{12} \leq z_1, \quad z_{12} \leq z_2, \quad z_{12} \geq z_1 + z_2 - 1$$

$$(z_1, z_2, z_{12}) \in [0, 1]^3$$

straightforward to obtain closed form soln.  
(see Martins et al).

• hard constraints;

- we might have factors that look like indicator funs

$$\text{eg } \phi_a(x_a) = \begin{cases} 0 & - x_a \text{ meets some test} \\ -\infty & \text{otherwise} \end{cases}$$

eg.

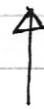
$$\phi_a(x_a) = \begin{cases} 0 & \text{if ~~one~~ exactly one of } x_a \\ & \text{is 1} \\ -\infty & \text{otherwise} \end{cases}$$

one hot x-OR factor.

Slave becomes, with work,

$$\min \|z - c\|^2$$

$$\text{st } z \in \text{conv } \mathcal{S}_A$$



accept set; all  $x_a$  st  
factor = 0

in one hot case, we have

(ii)

$$\min \|z - c\|^2$$

st  $z \in \text{Simplex}$



$$z \geq 0, \quad \mathbf{1}^T z = 1$$

equivalently, find point in Simplex  
closest to  $c$ .

- via sorting, Duchi '08