

Inequality constraints : Working set methods. ①

Notice from KKT that some inequality constraints are $\begin{cases} \text{active} \\ \text{bound} \\ \text{blocking} \end{cases}$ at soln, others aren't. Active constraints behave like equalities — others don't count.

IDEA :

- Search for active constraints while searching for point.
- Strategy :
 - start w feasible point
 - improve, while keeping feasible.
 - Maintain model of working set.
- We will only consider linear constraints

②

• assume we are at x_k .

• our model is

$$\min_x \quad x^T \frac{M}{2} x + d^T x.$$

st. $a_i^T x + b_i = 0$ } all active constraints

• here we want p st $x_{k+1} = x_k + p$

• so $\min_p \quad x_{k+1}^T \frac{M}{2} x_{k+1} + d^T x_{k+1}$

st $a_i^T x_{k+1} + b_i = 0$

substitute, get

$$\min_p \quad p^T \frac{G}{2} p + e^T p$$

st $a_i^T p = 0$

} active constraints

Q: How do we solve this?

Notice that $x_{k+1} + \alpha p$ is feasible for all α and all working constraints (3)

Cases:

(A) x_{k+1} is feasible for all constraints
(easy check — they're linear)
→ accept it.

(B) it isn't. — then there is some $\alpha \in [0, 1)$ st $x_k + \alpha p$ is feasible
(cause our working set is right — x_k is feasible in w.s)

Case B :

(4)

consider a constraint NOT in W.S.

if $\underline{a}_i^T p \geq 0$
then $\underline{a}_i^T (\underline{x}_k + \alpha p) \geq \underline{a}_i^T \underline{x}_k \geq b$

- ANY +ve α will work for this constraint.

if $\underline{a}_i^T p < 0$ then

$$\alpha_k \leq \frac{b_i - \underline{a}_i^T \underline{x}_k}{\underline{a}_i^T p_k}$$

Walk constraints to find smallest α_k .

constraints that have smallest α_k are active/blocking/etc.

(α_k could be zero if we're missing a constraint in working set.)

insert a blocking constraint into W_k
to get W_k

(6)

• ~~Main~~ Removing redundant constraints

Q: How do we know there is a constraint
in working set that shouldn't be
there?

A: Lagrange mult is -ve.

Q: Where did LM come from?

A: recipe for quadratic form st. linear

Overall story

6

- Start x_0 feasible
- Until finished
 - until x_k is minimizer of QP over working set
 - Take a step, and adjust W.S.
 - Minimizer when $p=0$
- Any -ve Lagrange multipliers?
 - Yes: remove one from W.S.
 - No: finished.

Check:

- at finished, KKT are true.

Concern:

- How much work to adjust W.S.?
- Could this cycle?
- What if constraints aren't linear?