# Basic Ray-Tracing Ideas -II

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# Recall: Randomized estimates of integrals

Weak law of large numbers

if 
$$x_i \sim p(x)$$
  
then  $\frac{1}{N} \sum_{i=1}^N f(x_i) \to \int f(x) p(x) dx$ 

- i.e. we can approximate integrals with sums
  - example: p(x) uniform, stochastic sampling of pixel
- generically, known as Monte Carlo estimates

# Importance weighting

if 
$$x_i \sim p(x)$$
  
then  $\frac{1}{N} \sum_{i=1}^N f(x_i) \to \int f(x) p(x) dx$ 

If 
$$x_i \sim p(x)$$

Then

$$\int f(x)dx \approx \frac{1}{N} \sum_{i} \frac{f(x_i)}{p(x_i)}$$

#### Randomized estimates and variance

$$\int f(x)dx \approx \frac{1}{N} \sum_{i} \frac{f(x_i)}{p(x_i)}$$

- The estimate is the value of a random variable
  - (different random samples -> different estimates)
  - whose expected value is the value of the integral
  - but whose variance might be very big
    - and is usually very hard to know
- Simple reasoning suggests that
  - p should be big when f is big, etc.

# Variance example



Drawing uniform samples will get a poor estimate -> draw samples mostly at peak and downweight

#### Algorithmic framework



Computational problem - what is L(ray)?

# Very simple ray-tracing

O Point light source



# Diffuse reflection

- Light leaves the surface evenly in all directions
  - cotton cloth, carpets, matte paper, matte paints, etc.
  - most "rough" surfaces
  - Parameter: Albedo
    - percentage of light arriving that leaves
    - range 0-1
      - practical range is smaller
- Test:
  - surface has same apparent brightness when viewed from different dir'ns

# Specular surface

- For some surfaces, reflection depends strongly on angle
  - mirrors (special case)
    - incoming direction, normal and outgoing direction are coplanar
    - angle din, normal and angle dout, normal are the same
  - more general cases later
  - rules:
    - din, dout, N coplanar
    - angle(din, N)=angle(dout, N)



# Lighting model

- Light arrives at a surface ONLY from a luminaire
  - this is an object that "makes light"
    - through chemical, mechanical, etc means
- Wild oversimplification, good for us right now
  - wait a few slides and it'll get more complicated

## Eye ray strikes diffuse surface







# Eye ray strikes specular surface

O Point light source

Compute brightness of specular surface at first contact = eye ray changes direction, and compute brightness at the end of that



# Implied computational problems

- Fast, accurate intersection with complicated models
  - Improved rendering
    - anti aliasing (= more rays)
    - motion blur (= more rays)
    - more complex illumination phenomena (= more rays, caching)

# Key idea - how bright is this point?

# Radiometry

#### • Questions:

- how "bright" will surfaces be?
- what is "brightness"?
  - measuring light
  - interactions between light and surfaces
- Core idea think about light arriving at a surface
  - around any point is a hemisphere of directions
  - what is important is what a source "looks like" to a receiver
    - receiver can't know anything else about source





#### Solid angle



FIGURE 2.15: A hemisphere on a patch of surface, to show our angular coordinates for computing radiometric quantities. The coordinate axes are there to help you see the drawing as a 3D surface. An infinitesimal patch of surface with area dA which is distance r away is projected onto the unit hemisphere centered at the relevant point; the resulting area is the solid angle of the patch, marked as  $d\theta d\phi$ . In this case, the patch is small so that the area and hence the solid angle is  $(1/r^2)dA\cos\theta_n$ , where  $\theta_n$  is the angle of inclination of the patch.

# Solid Angle

- By analogy with angle (in radians)
- The solid angle subtended by a patch area dA is given by



# Radiance

- Measure the "amount of light" at a point, in a direction the power (amount of energy per unit time) traveling at some point in a specified direction, per unit area *perpendicular to the direction of travel*, per unit solid angle.
- Units: watts per square meter per steradian (wm-2sr-1)
- Crucial property:
  - In a vacuum, radiance leaving p in the direction of q is the same as radiance arriving at q from p
  - hence the units

## Why not watts/square meter?

#### • Consider sphere radiating 1 W into vacuum

- Radius 1, center at origin
- Vacuum neither creates nor consumes power
- There's another sphere around it
  - Radius R, center at origin
  - Area 4 pi R^2
  - It can't collect more power than first sphere radiates so
    - watts/square meter must go down with distance....!!! (ew)



#### Radiance is constant along straight lines



# Irradiance

- How much light is arriving at a surface?
- Sensible unit is Irradiance
  - Incident power per unit area not foreshortened
  - This is a function of incoming angle.
- A surface experiencing radiance L(x,θ,φ) coming in from dω experiences irradiance

 $L(\mathbf{x}, \theta, \phi) \cos \theta d\omega$ 

• Crucial property: Total power arriving at the surface is given by adding irradiance over all incoming angles --- this is why it's a natural unit

#### Surfaces and the BRDF

- Many effects when light strikes a surface -- could be:
  - absorbed; transmitted. reflected; scattered
- Assume that
  - surfaces don't fluoresce
  - surfaces don't emit light (i.e. are cool)
  - all the light leaving a point is due to that arriving at that point
- Can model this situation with the Bidirectional Reflectance Distribution Function (BRDF)
- the ratio of the radiance in the outgoing direction to the incident irradiance

 $\rho_{bd}(\underline{x},\vartheta_o,\varphi_o,\vartheta_i,\varphi_i) =$ 

 $\frac{L_o(\underline{x}, \vartheta_o, \varphi_o)}{L_i(\underline{x}, \vartheta_i, \varphi_i) \cos \vartheta_i d\omega}$ 

# BRDF

- Units: inverse steradians (sr-1)
- Symmetric in incoming and outgoing directions
- Radiance leaving in a particular direction:
  - add contributions from every incoming direction

$$\int_{\Omega} \rho_{bd} (\underline{x}, \vartheta_o, \varphi_o, \vartheta_i, \varphi_i) L_i (\underline{x}, \vartheta_i, \varphi_i) \cos \vartheta_i d\omega_i$$

# Suppressing Angles - Radiosity

- In many situations, we do not really need angle coordinates
  - e.g. cotton cloth, where the reflected light is not dependent on angle
- Appropriate radiometric unit is radiosity
  - total power leaving a point on the surface, per unit area on the surface (Wm-2)
- Radiosity from radiance?
  - sum radiance leaving surface over all exit directions

$$B(\underline{x}) = \int_{\Omega} L_o(\underline{x}, \vartheta, \varphi) \cos \vartheta d\omega$$

### Exitance

- For some luminaires, generated light independent of angle
  - think light box
- Appropriate radiometric unit is exitance
  - total power leaving a point on the surface, per unit area on the surface (Wm-2), created in the surface

# Radiosity

- Important relationship:
  - radiosity of a surface whose radiance is independent of angle (e.g. that cotton cloth)

$$B(\underline{x}) = \int_{\Omega} L_o(\underline{x}, \vartheta, \varphi) \cos \vartheta d\omega$$
  
=  $L_o(\underline{x}) \int_{\Omega} \cos \vartheta d\omega$   
=  $L_o(\underline{x}) \int_{0}^{\pi/22\pi} \int_{0}^{\pi/22\pi} \cos \vartheta \sin \vartheta d\varphi d\vartheta$   
=  $\pi L_o(\underline{x})$ 









#### Lambertian surfaces and albedo

- For some surfaces, the BRDF is independent of direction
  - cotton cloth, carpets, matte paper, matte paints, etc.
  - radiance leaving the surface is independent of angle
  - Lambertian surfaces (same Lambert) or ideal diffuse surfaces
  - Use radiosity as a unit to describe light leaving the surface
  - percentage of incident light reflected is diffuse reflectance or albedo
- Useful fact:

$$\rho_{brdf} = \frac{\rho_d}{\pi}$$

# Specular surfaces

- Another important class of surfaces is specular, or mirrorlike.
  - radiation arriving along a direction leaves along the specular direction
  - reflect about normal
  - some fraction is absorbed, some reflected
  - on real surfaces, energy usually goes into a lobe of directions
  - can write a BRDF, but requires the use of funny functions



# Phong's model

- There are very few cases where the exact shape of the specular lobe matters.
- Typically:
  - very, very small --- mirror
  - small -- blurry mirror
  - bigger -- see only light sources as "specularities"
  - very big -- faint specularities
- Phong's model
  - reflected energy falls off with

 $\cos^n(\delta \vartheta)$ 



#### Lambertian + specular

- Widespread model
  - all surfaces are Lambertian plus specular component
- Advantages
  - easy to manipulate
  - very often quite close true
- Disadvantages
  - some surfaces are not
    - e.g. underside of CD's, feathers of many birds, blue spots on many marine crustaceans and fish, most rough surfaces, oil films (skin!), wet surfaces
  - Generally, very little advantage in modelling behaviour of light at a surface in more detail -- it is quite difficult to understand behaviour of L+S surfaces

# The Rendering Equation-1



Angle between normal and incoming direction

Radiance leaving a point in a direction

Radiance is constant along straight lines, so this is what we want to know

# The Rendering Equation - II

#### • This balance works for

- each wavelength,
- at any time, so

• So

$$L_o(\mathbf{x}, \omega_o, \lambda, t) = L_e(\mathbf{x}, \omega_o, \lambda, t) + \int_{\Omega} \rho_{bd}(\mathbf{x}, \omega_o, \omega_i, \lambda, t) L_i(\mathbf{x}, \omega_i, \lambda, t) \cos \theta_i d\omega_i$$


- Examples: diffuser boxes, white walls.
- The radiosity at a point due to an area source is obtained by adding up the contribution over the section of view hemisphere subtended by the source
  - change variables and add up over the source

#### Radiosity due to an area source

- rho is albedo
- E is exitance
- r(x, u) is distance between points
- u is a coordinate on the source



$$B(x) = \rho_d(x) \int_{\Omega} L_i(x, u \to x) \cos \theta_i d\omega$$
  
=  $\rho_d(x) \int_{\Omega} L_e(x, u \to x) \cos \theta_i d\omega$   
=  $\rho_d(x) \int_{\Omega} \left(\frac{E(u)}{\pi}\right) \cos \theta_i d\omega$   
=  $\rho_d(x) \int_{source} \left(\frac{E(u)}{\pi}\right) \cos \theta_i \left(\cos \theta_s \frac{dA_u}{r(x, u)^2}\right)$   
=  $\rho_d(x) \int_{source} E(u) \frac{\cos \theta_i \cos \theta_s}{\pi r(x, u)^2} dA_u$ 

#### Question: how to ray-trace this?



# Recall





#### Global illumination

$$L_o(\mathbf{x}, \omega_o) = L_e(\mathbf{x}, \omega_o) + \int_{\Omega} \rho_{bd}(\mathbf{x}, \omega_o, \omega_i) L_i(\mathbf{x}, \omega_i) \cos \theta_i d\omega_i$$

- Incoming radiance isn't just from luminaires
  - the reason you can see surfaces is they reflect light
  - other surfaces don't distinguish between reflected light and generated light



#### Question: how to ray-trace this?



# Recall





# Light paths

#### • Recursively expand, as above

- sample the incoming directions •
  - what radiance is coming in?  $\bullet$
  - go to far end what is emitted+reflected?
  - recur



#### Light paths - II

$$v = \int_{\Lambda} \int_{D} \int_{\Omega} \int_{T} w(\mathbf{x}, \lambda, \omega, t) L(\mathbf{x}, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(\text{ray}) L(\text{ray}) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda \approx \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \lambda, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega, t) L(x, \omega, t) dt d\omega dx d\lambda = \sum_{i \in \text{rays}} g(x, \omega, t) L(x, \omega$$

• But this is really (suppressing wavelength and time)

$$\int_{D} \int_{\Omega} L(\mathbf{x}, \omega) w(\mathbf{x}, \omega) dx d\omega \approx \frac{1}{N} \sum_{paths} (\text{contribution of path})$$

# Light paths - III



## Some light paths are harder than others

- We have already seen how to render
  - LDE (light diffuse eye)
    - eye ray to diffuse surface, can it see light?
  - LSE (light specular eye)
    - eye ray to specular surface, reflect and hit diffuse, can it see light?
  - Actually, can do:
    - LDS\*E (light diffuse 0 or more specular bounces eye)
- How about
  - LDDE (light diffuse diffuse eye)
    - easy geometry likely high variance
  - LS+DE (light diffuse at least one specular eye)
    - rather harder

#### Eye ray strikes diffuse surface - LDE

Compute brightness of diffuse surface at first contact = Can it see the light sources ?= Is there an object in line segment connecting point to source?





#### Eye ray strikes specular surface - LDSE

Compute brightness of specular surface at first contact = eye ray changes direction, and compute brightness at the end of that O Point light source



## Diffuse VS Specular (also translucent)

- Diffuse surfaces:
  - any incoming direction can cause light to travel down the eye ray
    - so you do not know from which directions contributions will arrive
  - when an eye ray arrives, it must create multiple query rays
- Specular surfaces:
  - only one incoming direction can cause light to travel down the eye ray
    - so you do know from which directions contributions will arrive
  - when an eye ray arrives, it creates only one query ray
- Translucent surfaces are like specular surfaces:
  - different geometry for the query ray

## LDD+E - easy geometry, but variance



#### LDD+E - variance control (sketch!)

- In principle, easily sampled recursively
- Preferentially sample paths that make large contributions
  - these are paths that connect light, eye, via high albedo surfaces
    - "Russian roulette"
      - continue path with probability = albedo
      - weight by (1/albedo)
- OR Cache results
  - propagating a path:
    - check: is there something in the cache?
      - yes: use it
      - no: propagate path and cache results

### LS+DE - harder - where is the light?



#### LS+DE - harder - where is the light?



Problem: which direction leaving diffuse surface will hit the light?

## Strategies

#### • Bidirectional ray tracing

- Trace a lot of rays from light through specular surfaces to first diffuse
- Trace a lot of eye rays to first diffuse
- Join paths
- Variance control
  - weight paths as if they'd been found in different ways (Veach +Guibas)
- Markov chain monte carlo
  - take a path and mutate it; reweight contribution of mutated path
- Caching
  - Photon cache trace many rays from light through specular to diffuse
    - cache at diffuse
    - query with eye ray

#### Biased vs unbiased rendering

#### • Unbiased renderer

- pixel value is value of random variable (different paths=different values)
- E(estimate)=True value
- sometimes essential
  - eg estimate the amount of light in a museaum hall
- Biased renderer
  - E(estimate)=True value + Bias
  - eg Photon map (as above)
    - Bias because we do not know how many photons to stick in cache
  - Often more realistic
- Crucial point
  - Very few people can tell if a render is nearly physically correct
    - and no-one can reliably spot exactness

## The plenoptic function

- We are repeatedly sampling radiance
  - as function of point, direction
- What if we had a function that could report that?
- Plenoptic function
  - radiance along a directed line
  - space of lines is rather nastier than you might think

# The plenoptic function as a cache





#### The plenoptic function - careful!

#### • This is a function whose domain is nasty

- all maximal directed line segments (lines) in free space
- the domain can get very complicated
  - easy when there aren't any objects
  - otherwise, much harder
- domain is sometimes called a visibility complex



Fig. 1. Maximal free segment. (a) All the rays collinear to r whose origin is between the two spheres "see" point B. (b) These rays are grouped into a maximal free segment S. Two other maximal free segments S and S'' are collinear to S.

#### Durand et al 02

## Lines in 3D (if it's empty!)

#### • Space of lines is 4 dimensional

- can specify a line by:
  - where it intersects each of two planes
    - some missing lines, some details
- alternative
  - directed line
  - point on the tangent plane of sphere





#### Lines in 3D with object can be nasty



Fig. 1. Maximal free segment. (a) All the rays collinear to r whose origin is between the two spheres "see" point B. (b) These rays are grouped into a maximal free segment S. Two other maximal free segments S and S'' are collinear to S.

Durand et al 02

# Simplify

- Place an object in a box
  - record radiance for each ray leaving box
- Easy to ray trace
  - look up eye ray in rays leaving box
    - report that value
- Capture is relatively easy



## Capturing this representation

- Obtain an awful lot of images from calibrated cameras
  - each image is a set of rays leaving the box
  - calibration





Figure 10: Object and lighting support. Objects are mounted on a Bogen fluid-head tripod, which we manually rotate to four orientations spaced 90 degrees apart. Illumination is provided by two 600W Lowell Omni spotlights attached to a ceilingmounted rotating hub that is aligned with the rotation axis of the tripod. A stationary 6'  $\mathbf{x}$  6' diffuser panel is hung between the spotlights and the gantry, and the entire apparatus is enclosed in black velvet to eliminate stray light.

Levoy and Hanrahan, 96

#### Rendering



Figure 12: The process of resampling a light slab during display.

Levoy+Hanrahan, 96

## Issue: Sampling and Interpolation



Figure 12: The process of resampling a light slab during display.

- Almost every eye ray ends up "between" uv, st samples
  - we must interpolate (smooth; something)
  - Traditional: multilinear interpolation

#### Interpolation helps, but..



**Figure 13:** The effects of interpolation during slice extraction. (a) No interpolation. (b) Linear interpolation in uv only. (c) Quadra-linear interpolation in uvst.



Figure 3: Using line space to visualize ray coverage. (a) shows a single

#### Revise model

#### • We need:

- better interpolation
- easier capture
- some way to deal with the awkwardness of line representations
- Ideas:
  - move to scattering/volume rendering based representation
    - this will make the line representation easier to deal with
  - use a multilayer perceptron to represent relevant functions
# Scattering

- Fundamental mechanism of light/matter interactions
- Visually important for
  - slightly translucent materials (skin, milk, marble, etc.)
  - participating media
- In fact, it's the mechanism underlying reflection

# Participating media

#### • for example,

- smoke,
- wet air (mist, fog)
- dusty air
- air at long scales
- Light leaves/enters a ray travelling through space
  - leaves because it is scattered out
  - enters because it is scattered in
- New visual effects

#### Light hits a small box of material



# A ray passing through scattering material



### Airlight as a scattering effect







From Lynch and Livingstone, Color and Light in Nature





From Lynch and Livingstone, Color and Light in Nature

## Rendering this



• Ignore in-scattering

- only account for forward scattering
- Assume there is a source at t=T
  - of intensity I(T)
  - what do we see at t=0?



$$\frac{dI}{dt} = \sigma(t)I(t)$$
$$\frac{d\log I}{dt} = \sigma(t)$$

$$I(T) = I(0)e^{\int_0^T \sigma(t)dt} \qquad I(0) = I(T)e^{-\int_0^T \sigma(t)dt}$$

#### Yields

The volume density  $\sigma(\mathbf{x})$  can be interpreted as the differential probability of a ray terminating at an infinitesimal particle at location  $\mathbf{x}$ . The expected color  $C(\mathbf{r})$  of camera ray  $\mathbf{r}(t) = \mathbf{o} + t\mathbf{d}$  with near and far bounds  $t_n$  and  $t_f$  is:

$$C(\mathbf{r}) = \int_{t_n}^{t_f} T(t)\sigma(\mathbf{r}(t))\mathbf{c}(\mathbf{r}(t),\mathbf{d})dt, \text{ where } T(t) = \exp\left(-\int_{t_n}^t \sigma(\mathbf{r}(s))ds\right).$$
(1)

Mildenhall et al, 20