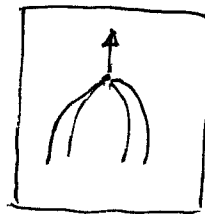
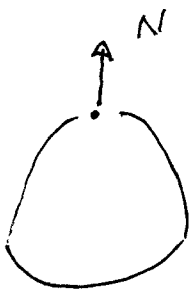


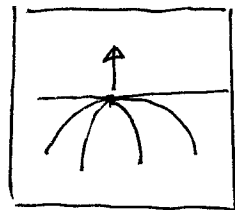
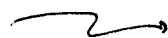
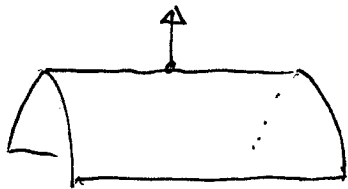
Local (Differential) Geometry of Surfaces:

Choose a point on a surf.

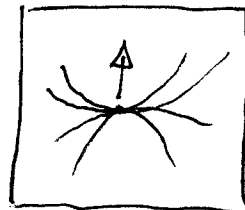
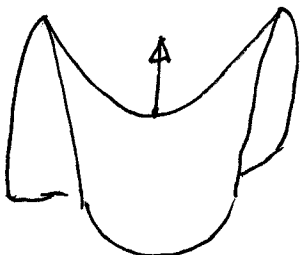
- compute normal
- Build family of planes thru pt, normal
- consider these X-sections of surf
- 3 cases



Elliptic



Parabolic

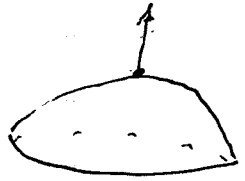


Hyperbolic

A finer
helpful

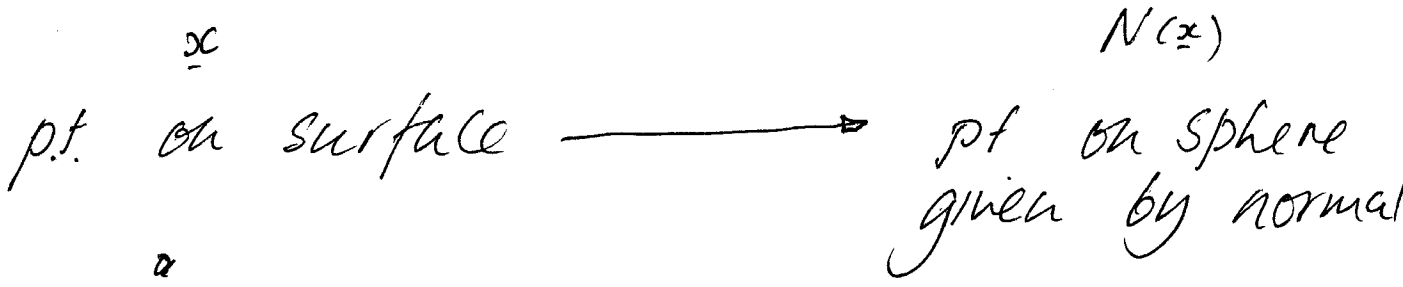
classification

would be

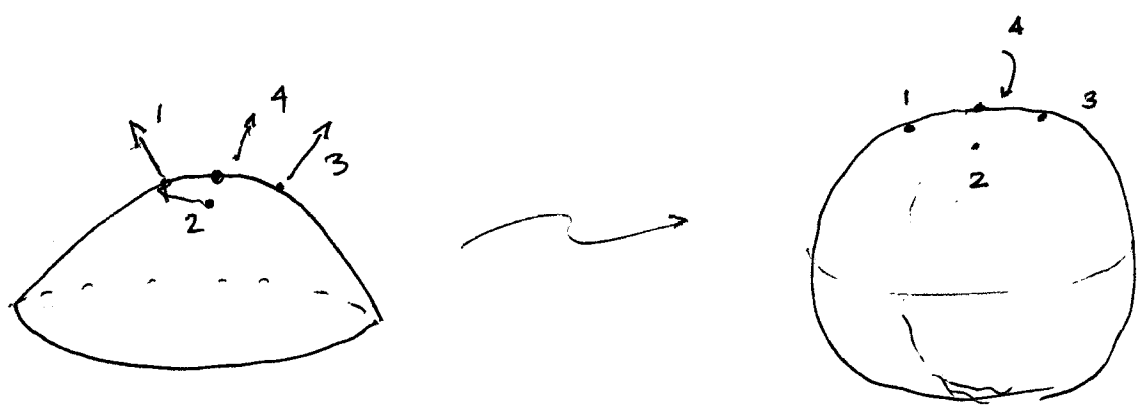


Both Elliptic

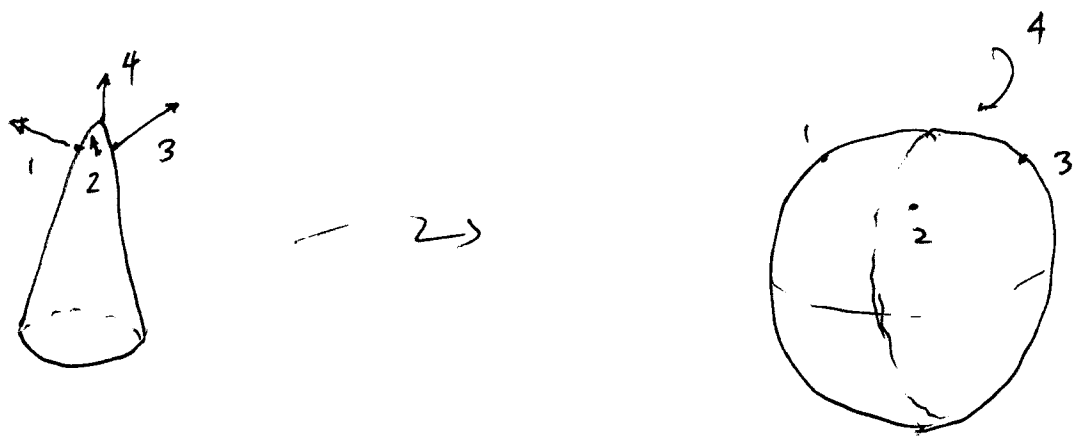
We get this from the Gauss map.



I



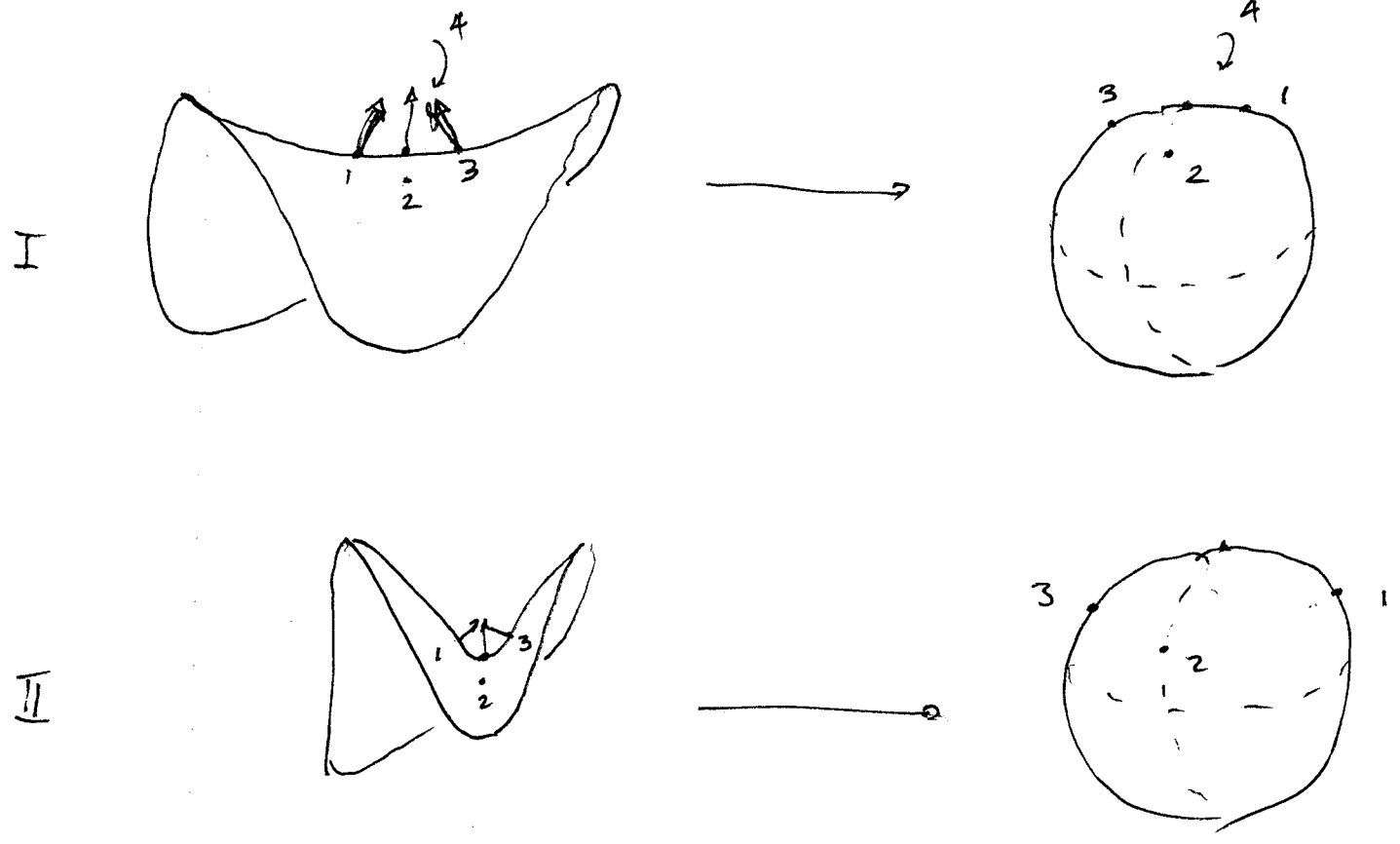
II



- map a small circle round p to sphere

- case I : small circle
small \downarrow "

- case II : small \rightarrow big.

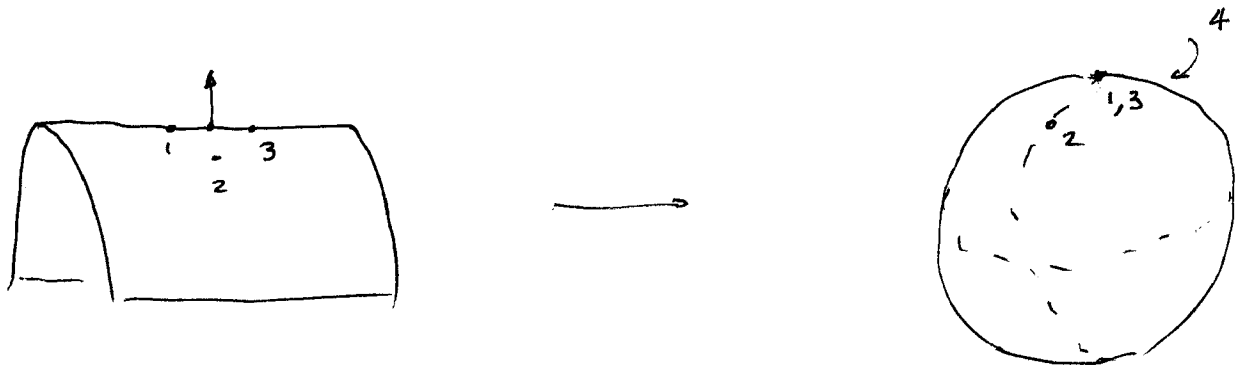


• Notice direction reverses

I: small → small

II: small → big

5



• small \rightarrow area zero.

Defn

K = Gaussian curvature

$$= \lim_{\text{radius} \rightarrow 0} \left\{ \frac{\text{Area of Gauss map}}{\text{Area on surf}} \right\}$$

$K = \begin{cases} < 0 & \text{Hyperbolic} \\ 0 & \text{Parabolic} \\ > 0 & \text{Elliptic} \end{cases}$

Surface is

$$(x, y, z(x, y))$$

$$\approx \left(x, y, z_0 + (\nabla z) \cdot (x, y) + \frac{1}{2} \begin{pmatrix} x \\ y \end{pmatrix}^T H \begin{pmatrix} x \\ y \end{pmatrix} + O(x, y)^3 \right)$$

but $z_0 = 0$
 $\nabla z = 0$

So $(x, y, z(x, y)) = \left(x, y, \underbrace{\frac{1}{2} \begin{pmatrix} x \\ y \end{pmatrix}^T H \begin{pmatrix} x \\ y \end{pmatrix}}_{\text{quadratic form}} + O(3) \right)$

- this is a quadratic form
- symmetric

\therefore rotate coord sys

$$(u, v, z(u, v)) = \left(u, v, \frac{1}{2} (k_1 u^2 + k_2 v^2) + O(3) \right)$$

Now recall a curve

$(u, \frac{1}{2} au^2)$ has curvature a
at $u=0$

So the curvature of the ~~the~~
 u section is K_1

v " is K_2

~~$s = u \cos \theta + v \sin \theta$~~ "

$s = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}$ " is $K_1 \cos^2 \theta + K_2 \sin^2 \theta$

\therefore The directional curvature has

maximum $\max(K_1, K_2)$

min $\min(K_1, K_2)$

∴ at each point on Surf, there are 2 dir's, orthonormal, where dir' curvature is max, resp. min

Principal { directions
curvatures

• With easy extra work

$$K = k_1 k_2$$

• Normal curvature is

$$H = k_1 + k_2$$

this gives bending.

we have $H = \begin{bmatrix} k_1 & 0 \\ 0 & k_2 \end{bmatrix}$ as a local

Description. We can see this as

a quadratic form on tangent vecs

$X_k = \begin{pmatrix} x_u \\ x_v \end{pmatrix}$ in u, v coords

$Y = \begin{pmatrix} y_u \\ y_v \end{pmatrix}$ in " coords

$X^T H Y$ is quadratic form

Important cases

$$X^T H Y = 0$$

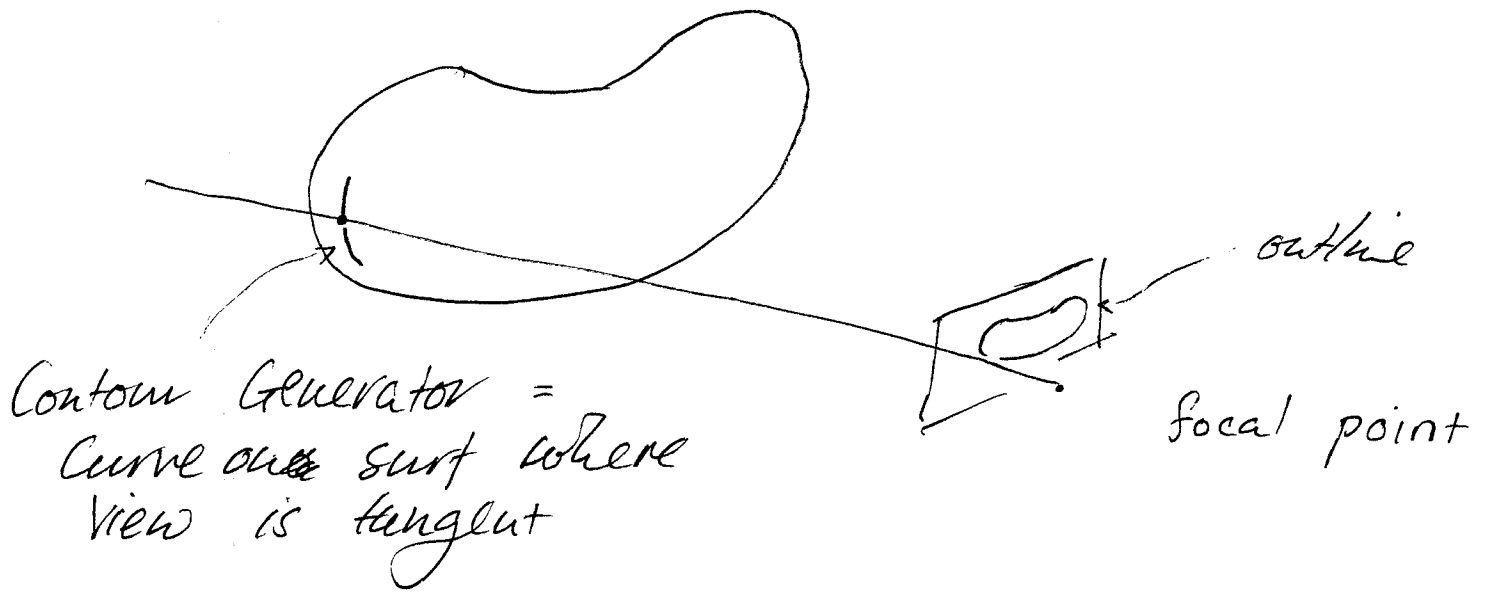
X, Y are conjugate

$$X^T H X = 0$$

X is asymptotic

Conjugate dirs have an important application

§ Important phenomenon.



• C.G., outline move when view
moves.

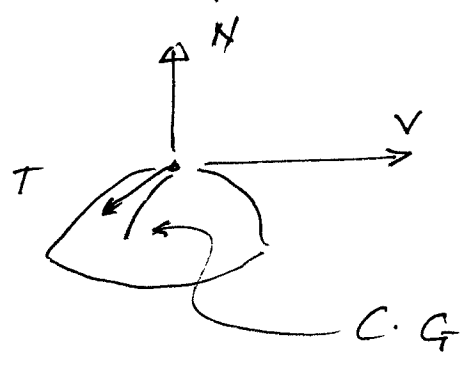
at C.G.

$$V \cdot N = 0$$

Q: what is tangent to C.G.?

~~at our~~

• Assume our point is ~~surface~~ C.G. pt



$$N \cdot V = 0$$

• now, we want the C.G. tangent T

- T tangent to surface
- directional derivative of $(N \cdot V)$ in T direction is 0

$$(D_T (N \cdot V) = 0)$$

$$T = (a, b)$$

$$D_T = a \frac{\partial}{\partial u} + b \frac{\partial}{\partial v}$$

compute N

$$(u, v, \frac{1}{2} k_1 u^2 + \frac{1}{2} k_2 v^2)$$

$$N = \frac{-k_1 u, -k_2 v, 1}{\sqrt{1 + k_1^2 u^2 + k_2^2 v^2}}$$

notice magnitude of n has nothing to do with problem.

$$V = (v_0, v_1, v_2) \quad \left[\text{orthographic case} \right]$$

$$N \cdot V = 0 \quad \propto \quad -k_1 u v_0 - k_2 v v_1 + v_2$$

$$a [-k_1 v_0] + b [-k_2 v_1] = 0$$

\equiv V and T are conjugate

Useful ideas

- it is often difficult to construct the coordinate system we have used.

eg parametric surface

$$\underline{X}(s,t) = (x(s,t), y(s,t), z(s,t))$$

at s, t there are 2 tangents X_s, X_t

$$\left(X_s = \frac{\partial X}{\partial s}, \quad X_t = \frac{\partial X}{\partial t} \right)$$

if V is a tangent vector, how long is it?

$$V = a X_s + b X_t$$

$$V \cdot V = \begin{bmatrix} a \\ b \end{bmatrix}^T \begin{bmatrix} X_s \cdot X_s & X_s \cdot X_t \\ X_s \cdot X_t & X_t \cdot X_t \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

this matrix $\begin{bmatrix} X_s \cdot X_s & X_t \cdot X_s \\ X_t \cdot X_s & X_t \cdot X_t \end{bmatrix}$ is the

FIRST FUNDAMENTAL FORM

Notice

$$N \cdot N = 1$$

Now consider a tangent vector V
• the directional derivative in the V direction is

$$a \frac{\partial}{\partial s} + b \frac{\partial}{\partial t}$$

if $V = aX_s + bX_t$

• write D_V

• $D_V (N \cdot N) = 0$

so

$$(D_V N) \cdot N = 0$$

so

$D_V N$ is a tangent vector

for u a tangent vector,

$$(D_V N) \cdot u = \text{II}(u, v)$$

$\text{II}(u, v)$ is a quadratic form in u, v

SECOND FUNDAMENTAL FORM

$$K = \frac{\det \text{II}}{\det \text{I}}$$

Our form \mathbb{H} is second fundamental form

u, v are
conjugate dirs if $\mathbb{II}(u, v) = 0$