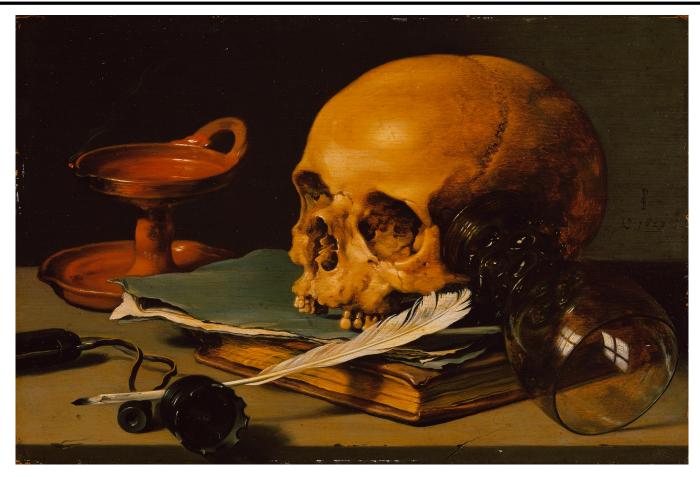
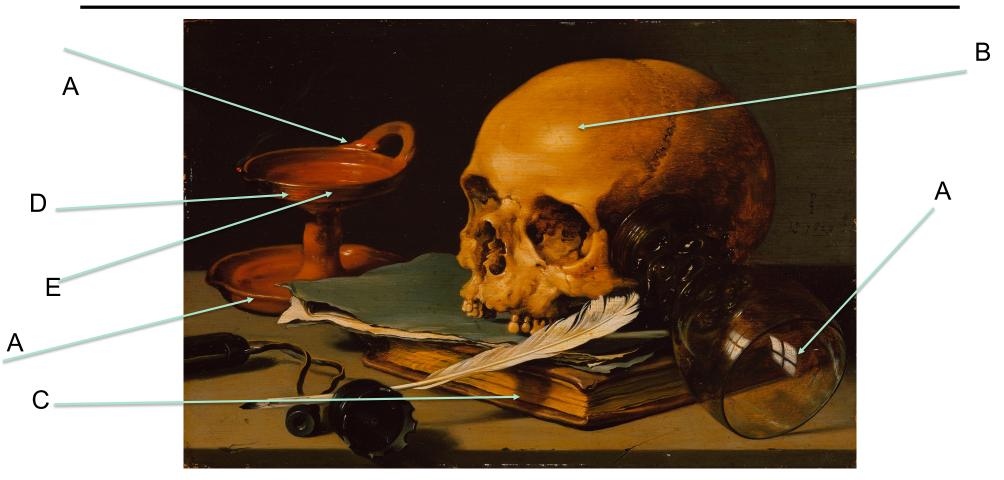
### Light and shading



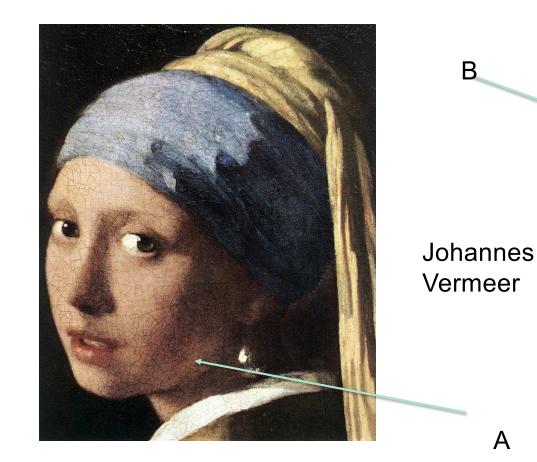
P. Claesz, Still Life with a Skull and a Writing Quill, 1628

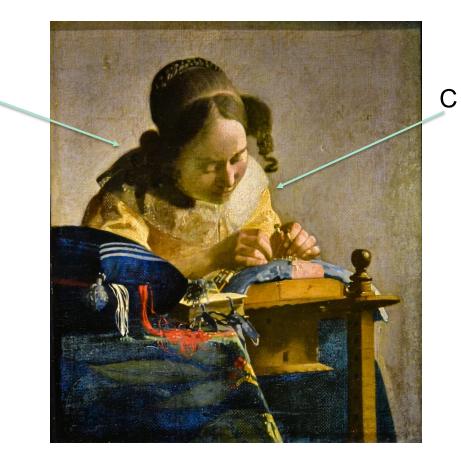
### Some phenomena

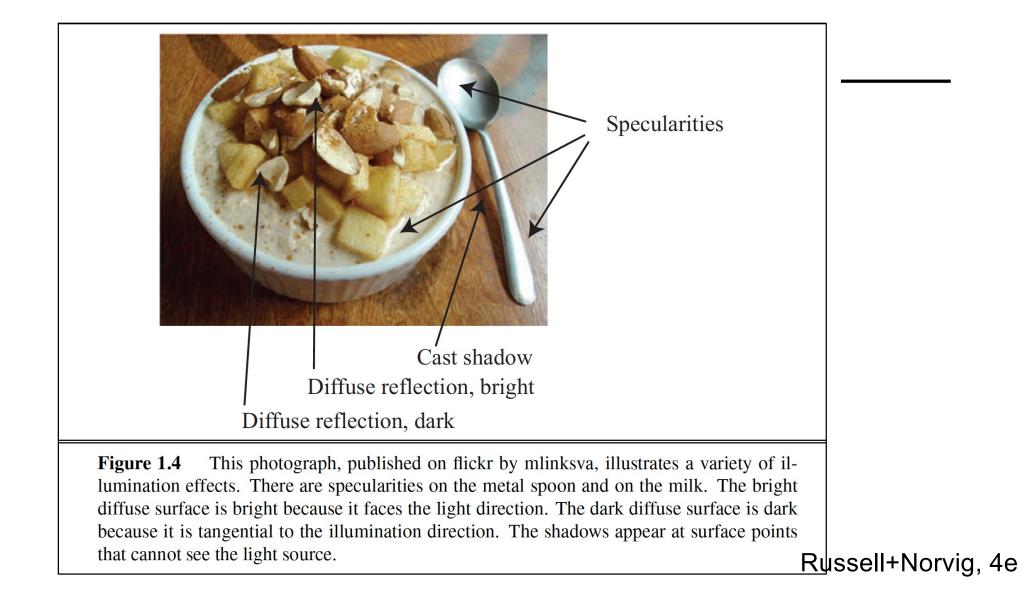


P. Claesz, Still Life with a Skull and a Writing Quill, 1628

### Artist physics can't be trusted!

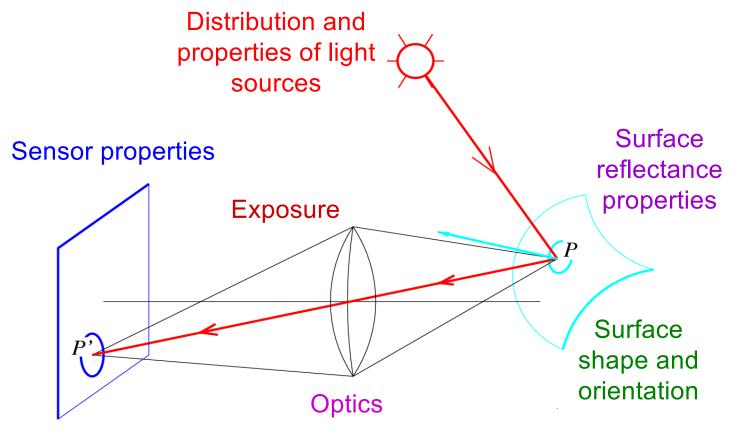






## Image formation

• What determines the *brightness* of an image pixel?

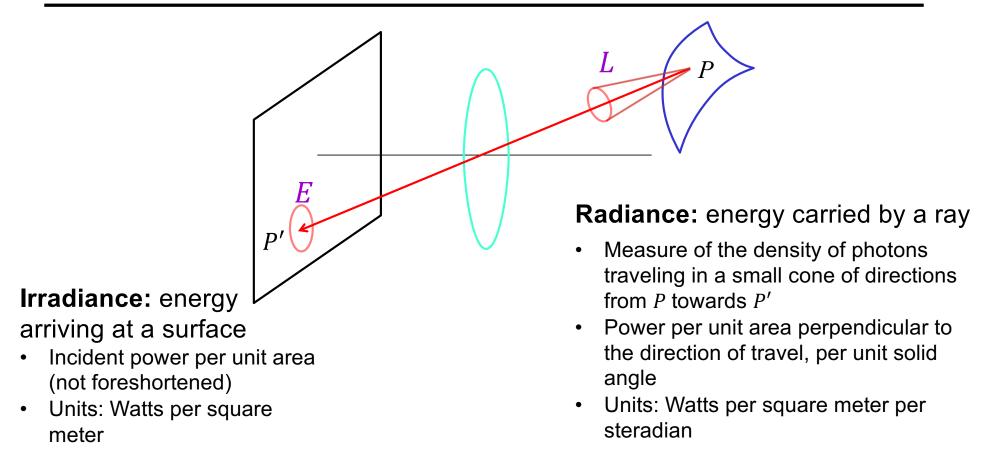


Slide by L. Fei-Fei

# Outline

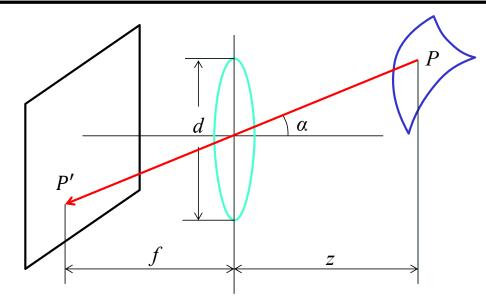
- Small taste of radiometry
- In-camera transformation of light
- Reflectance properties of surfaces
- Diffuse and specular reflection
- Shape from shading
- Estimating direction of light sources

# Radiometry of image formation



#### What is the relationship between E and L?

### Fundamental radiometric relation

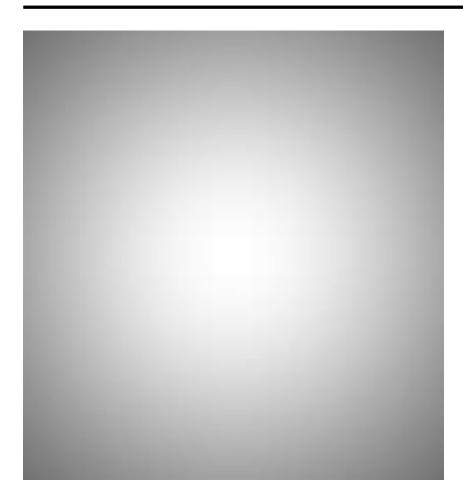


$$E = \left[\frac{\pi}{4} \left(\frac{d}{f}\right)^2 \cos^4 \alpha\right] L$$

- Image irradiance (E) is linearly related to scene radiance (L)
- Irradiance is *directly* proportional to the area of the lens  $(\frac{\pi d^2}{4})$  and *inversely* proportional to the squared distance between the lens and the image plane (*f*)
- The irradiance decreases as the angle between the viewing ray and the optical axis (α) increases

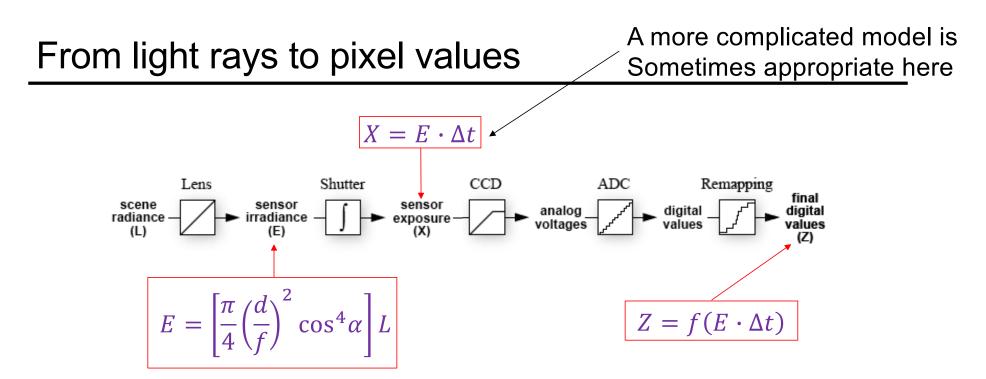
For derivation, see, e.g., Szeliski 2.2.3

### Fundamental radiometric relation



$$E = \left[\frac{\pi}{4} \left(\frac{d}{f}\right)^2 \cos^4 \alpha\right] L$$

S. B. Kang and R. Weiss. <u>Can we calibrate a camera</u> <u>using an image of a flat, textureless Lambertian surface?</u> ECCV 2000



- **Camera response function**: the mapping *f* from irradiance to pixel values
  - Needed for applications like estimation of scene reflectance properties, creating high dynamic range (HDR) images
  - For further reading: M. Brown, <u>Understanding the In-Camera Image Processing Pipeline</u> for Computer Vision, CVPR 2016 Tutorial

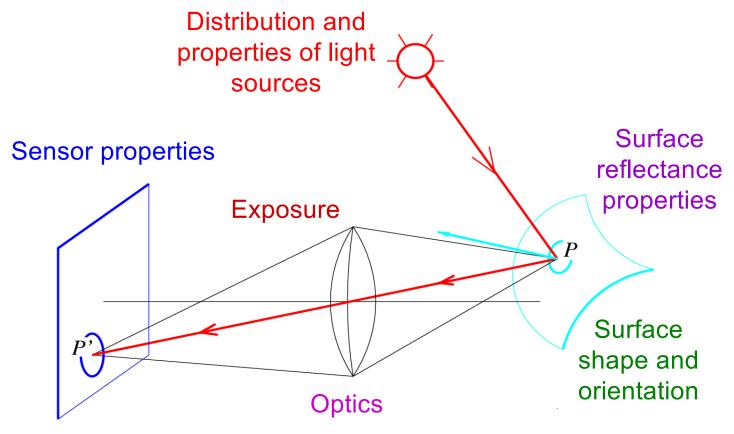
Figure source: P. Debevec and J. Malik. <u>Recovering High Dynamic Range Radiance Maps from Photographs</u>. SIGGRAPH 1997

# Outline

- Small taste of radiometry
- In-camera transformation of light
- Reflectance properties of surfaces

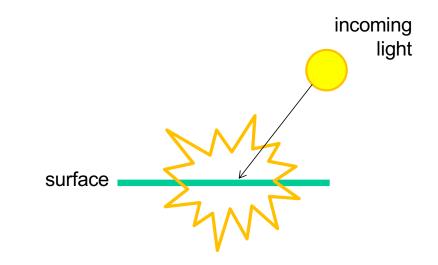
Recall: Image formation

• What determines the brightness of an image pixel?



Slide by L. Fei-Fei

# What can happen to light when it hits a surface?



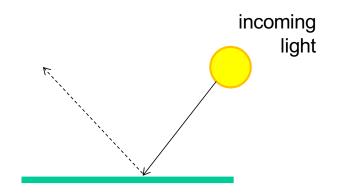
# Basic models of reflection

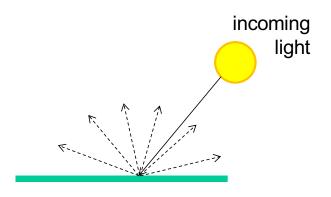
• **Specular reflection:** light is reflected about the surface normal



• **Diffuse reflection:** light scatters equally in all directions

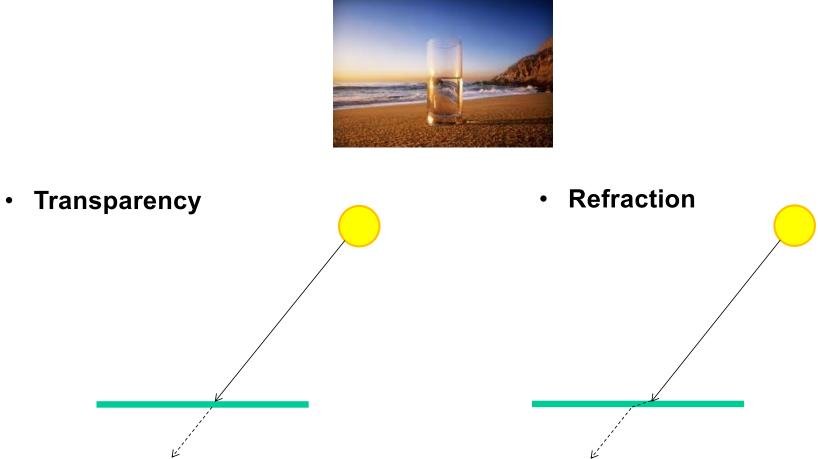






Slide from D. Hoiem

### Other possible effects

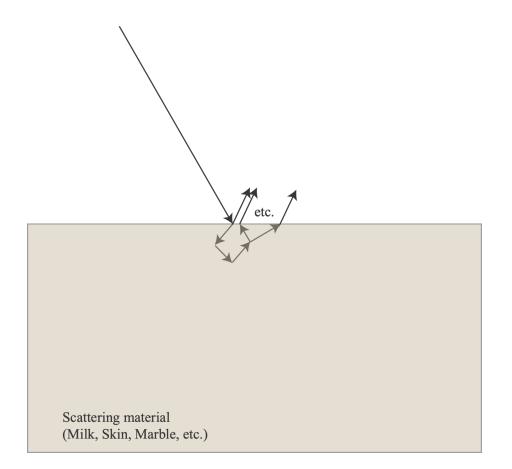


Slide from D. Hoiem

### Other possible effects

Subsurface scattering





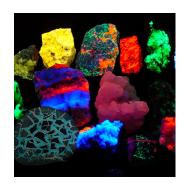
Slide from D. Hoiem Image source

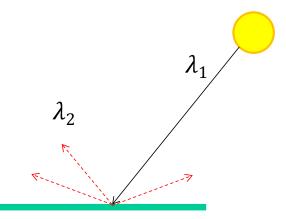


subsurface scattering in skin (not rendered!)

### Other possible effects

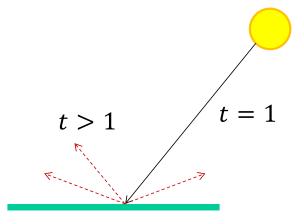
• Fluorescence





Phosphorescence



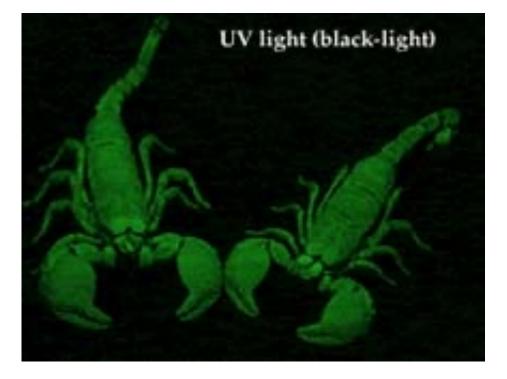


Slide from D. Hoiem

### Fluorescence in nature

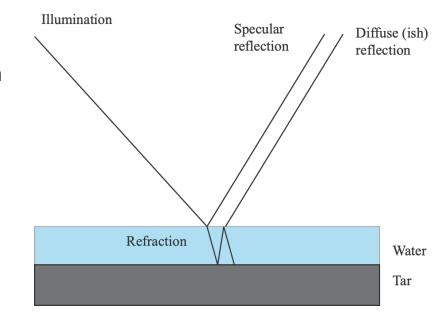
Many examples, mostly obscure: scorpions, deep sea fish, teeth, nylon, chitons





### Films on surfaces

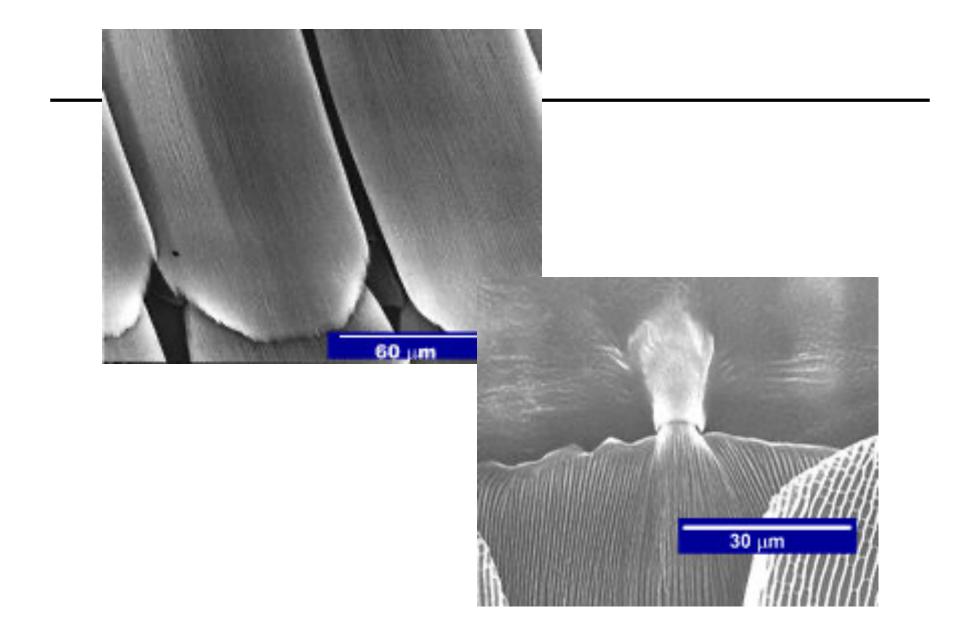
- eg water
- Assume:
  - film is thin
- You see:
  - specular reflection+diffuse term

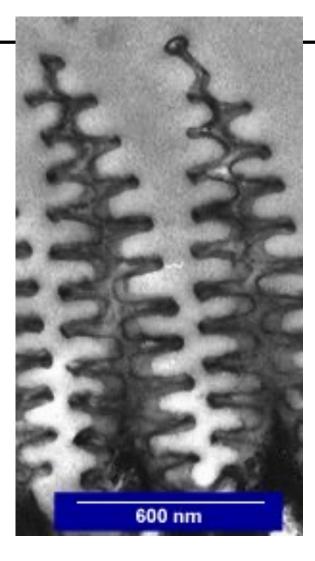


### Interference effects

#### Sometimes seen on films

- if the film is the right number of wavelengths thick
  - waves will interfere destructively (resp constructively)
  - can give rise to intense colors
    - oil films on water often do this

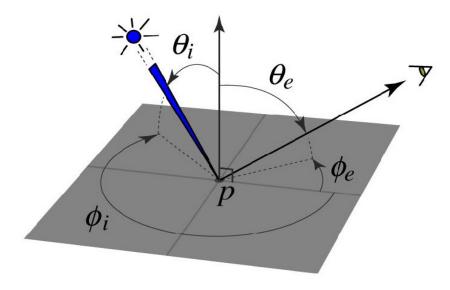






# Bidirectional reflectance distribution function (BRDF)

- How bright a surface appears when viewed from one direction when light falls on it from another
- Definition: ratio of the radiance in the emitted direction to irradiance in the incident direction



Function of (at least) four parameters: incident and outgoing  $\theta$ ,  $\phi$ 

Source: Steve Seitz

# Bidirectional reflectance distribution function (BRDF)

- Table of what goes out vs what went in
- Definition:
  - ratio of the radiance in the emitted direction to irradiance in the incident direction
- Can be measured (goniometry), but measurement is expensive
- Can be incredibly complicated and is often wildly unstable!



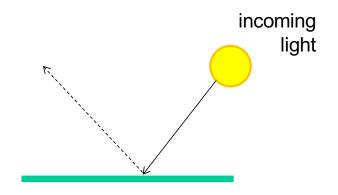
# Basic models of reflection in detail

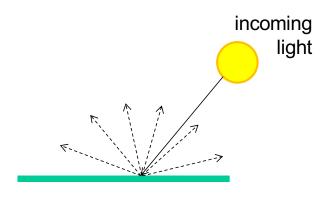
• **Specular reflection:** light is reflected about the surface normal



• **Diffuse reflection:** light scatters equally in all directions



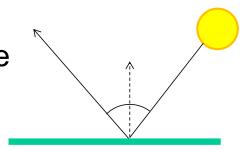




Slide from D. Hoiem

# Specular reflection

 Radiation arriving along a source direction leaves along the **specular direction** (source direction reflected about normal)



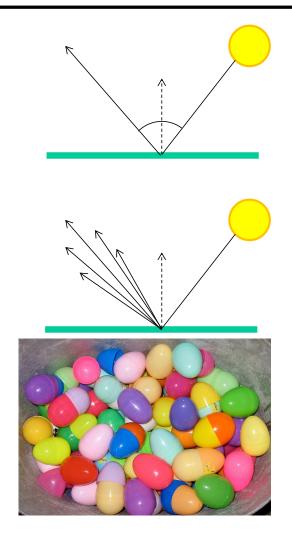
- Classic case: Mirror
- Diagnosis
  - When you look at a specular surface from different directions, appearance changes
  - True specular surfaces are "really like" mirrors
    - Form a clear image
- Q:
  - Why do mirrors reverse left and right, but not up and down?

# **Specularities**

- On real surfaces, energy usually goes into a "lobe" of directions
  - So image is blurred
  - More usually, you see only the source

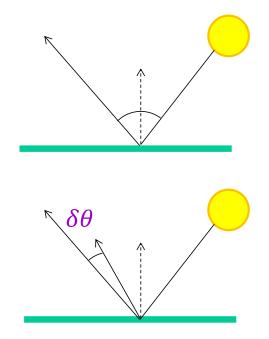
#### Specularities: narrow bright patches

- On metals: color of the metal
- Others: color of the light source

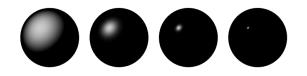


Specular reflection

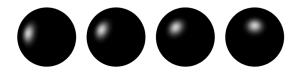
• **Phong model:** reflected energy falls of with  $\cos^{n}(\delta\theta)$ 



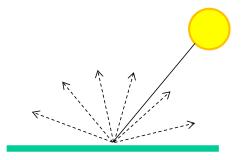
#### Changing the exponent



#### Moving the light source

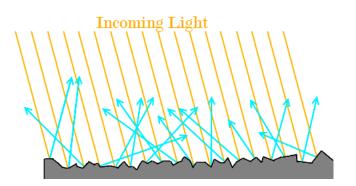


- Light scatters equally in all directions
  - E.g., brick, matte plastic, rough wood



- Light scatters equally in all directions
  - E.g., brick, matte plastic, rough wood

 One cause: *microfacets* that scatter incoming light randomly



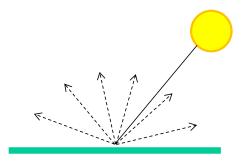
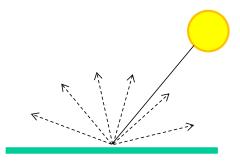




Image source

- Light scatters equally in all directions
  - E.g., brick, matte plastic, rough wood

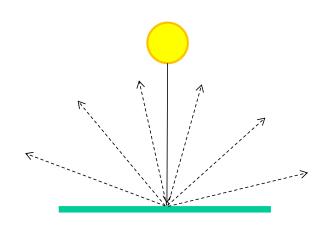


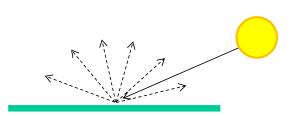
- Diagnosis:
  - Surface has the same brightness when looked at from different directions
    - (under fixed illumination)
- Extremely common
  - Very often surfaces are "largely" diffuse

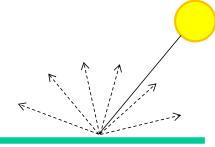
Image source

- Light scatters equally in all directions
  - For a fixed incidence angle, BRDF is constant

• What if we change the incidence angle?

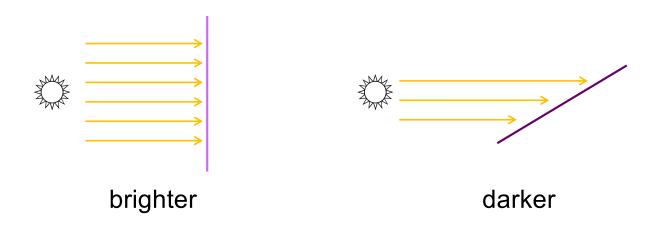


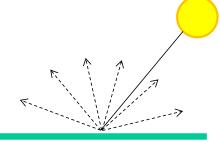




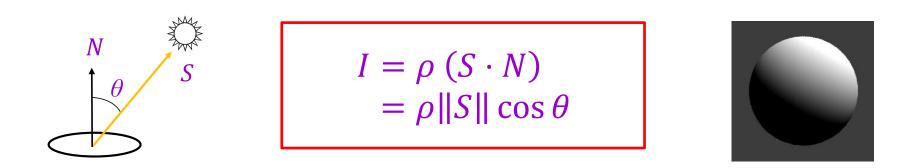
- Light scatters equally in all directions
  - For a fixed incidence angle, BRDF is constant





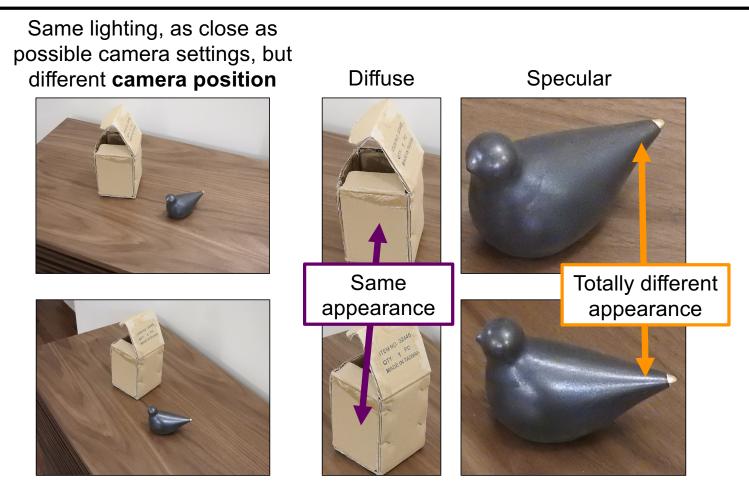


# Diffuse reflection: Lambert's law



- *I*: reflected intensity (technically: *radiosity*, or total power leaving the surface per unit area)
- $\rho$ : albedo (fraction of incident irradiance reflected by the surface)
- *S*: direction of light source (magnitude proportional to intensity of the source)
- N: unit surface normal

## Diffuse vs. specular: Significance for vision applications



Source: J. Johnson and D. Fouhey

# Outline

- Small taste of radiometry
- In-camera transformation of light
- Reflectance properties of surfaces
- Diffuse and specular reflection
- Shape from shading

# Photometric stereo, or shape from shading

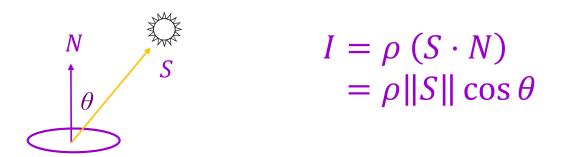
Can we reconstruct the shape of an object based on shading cues?



Luca della Robbia, *Cantoria*, 1438

### Photometric stereo, or shape from shading

- Can we reconstruct the shape of an object based on shading cues?
- Assuming a Lambertian object, given the image intensity (I), can we recover the light source direction (S) and the surface normal (N)?
- Can we do this from a single image?



### Shape from shading ambiguity





Source: J. Johnson and D. Fouhey

Image source

# Shape from shading ambiguity

 Humans assume light from above (and the blueness also tells you distance)

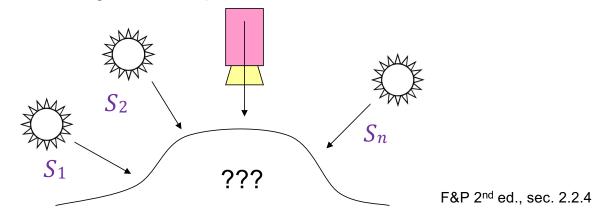


Source: J. Johnson and D. Fouhey

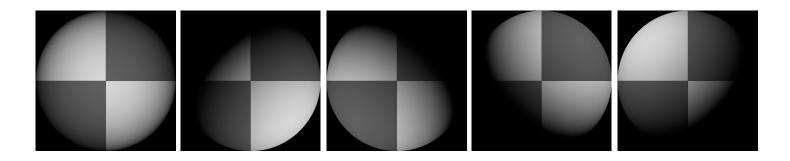
Image source

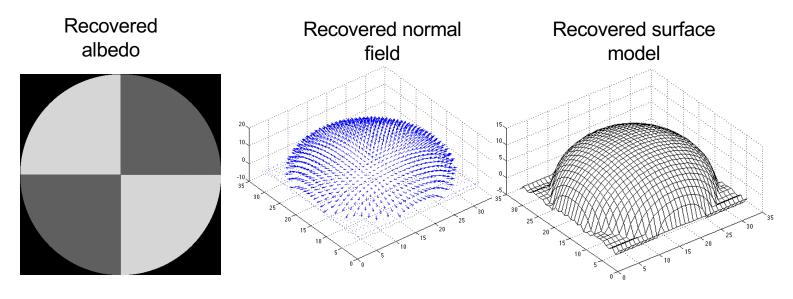
#### Photometric stereo

- Assume:
  - A Lambertian object
  - A *local shading model* (each point on a surface receives light only from sources visible at that point)
  - A set of *known* light source directions
  - A set of pictures of an object, obtained in exactly the same camera/object configuration but using different sources
  - Orthographic projection
- Goal: reconstruct object shape and albedo



### Example 1





### Example 2

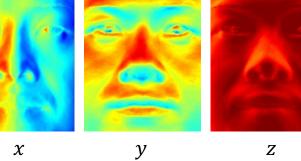
Input

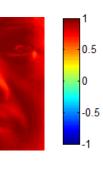


Recovered albedo



Recovered normal field





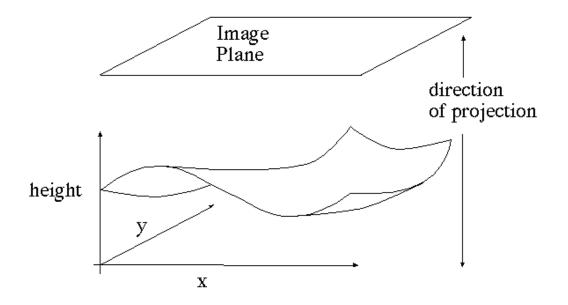
>

Recovered surface model



Image model

- Known: source vectors  $S_j$  and pixel values  $I_j(x, y)$
- **Unknown:** surface normal N(x, y) and albedo  $\rho(x, y)$



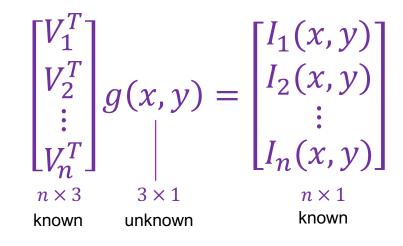
#### Image model

- Known: source vectors  $S_j$  and pixel values  $I_j(x, y)$
- **Unknown:** surface normal N(x, y) and albedo  $\rho(x, y)$
- Assume that the response function of the camera is a linear scaling by a factor of k
- Lambert's law:

$$I_{j}(x, y) = k \rho(x, y) (N(x, y) \cdot S_{j})$$
$$= (\rho(x, y)N(x, y)) \cdot (k S_{j})$$
$$= g(x, y) \cdot V_{j}$$

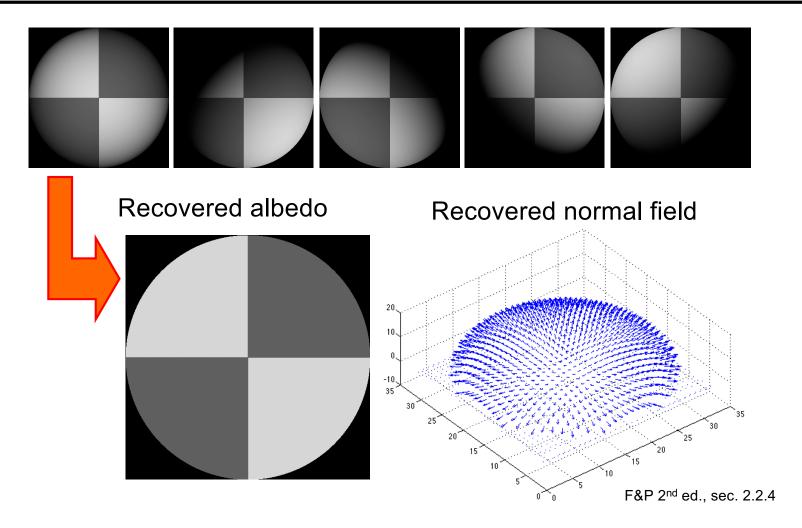
#### Least squares problem

• For each pixel, set up a linear system:



- Obtain least-squares solution for g(x, y), which we defined as  $\rho(x, y)N(x, y)$
- Since N(x, y) is the *unit* normal,  $\rho(x, y)$  is given by the magnitude of g(x, y)
- Finally,  $N(x, y) = \frac{1}{\rho(x, y)} g(x, y)$

### Synthetic example



#### Recovering a surface from normals

• Recall: the surface is written as • Write the estimated vector g as

(x, y, f(x, y))

 $g(x,y) = \begin{bmatrix} g_1(x,y) \\ g_2(x,y) \\ g_3(x,y) \end{bmatrix}$ 

- This means the unit normal has the following form:
- Then we obtain values for the partial derivatives of the surface:

$$N(x, y) = \frac{1}{\sqrt{f_x^2 + f_y^2 + 1}} \begin{bmatrix} f_x \\ f_y \\ 1 \end{bmatrix}$$

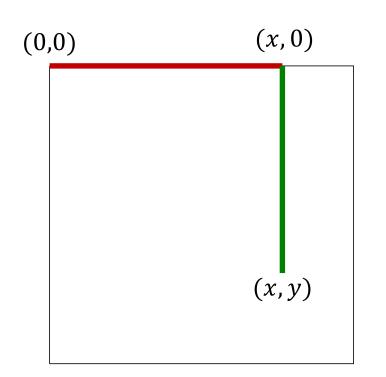
$$f_x(x,y) = \frac{g_1(x,y)}{g_3(x,y)}$$
$$f_y(x,y) = \frac{g_2(x,y)}{g_3(x,y)}$$

### Recovering a surface from normals

• We can now recover the surface height at any point by integration along some path, e.g.

f(x, y) = $\int_0^x f_x(s, 0)ds + \int_0^y f_y(x, t)dt + C$ 

 For robustness, it is better to take integrals over many different paths and average the results



### Recovering a surface from normals

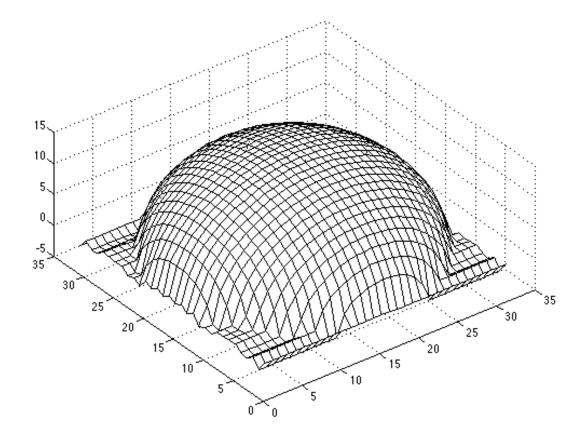
• We can now recover the surface height at any point by integration along some path, e.g.

f(x,y) = $\int_0^x f_x(s,0)ds + \int_0^y f_y(x,t)dt + C$ 

 For robustness, it is better to take integrals over many different paths and average the results  Note: *integrability* must be satisfied: for the surface *f* to exist, the mixed second partial derivatives must be equal (or at least similar in practice):

$$\frac{\partial}{\partial y} \left( \frac{g_1(x, y)}{g_3(x, y)} \right) = \frac{\partial}{\partial x} \left( \frac{g_2(x, y)}{g_3(x, y)} \right)$$

### Surface recovered by integration



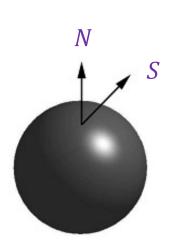
F&P 2<sup>nd</sup> ed., sec. 2.2.4

# Limitations of model

- Orthographic camera model
- Simplistic reflectance and lighting model
- No shadows
- No interreflections
- No missing data
- Integration is tricky

# Outline

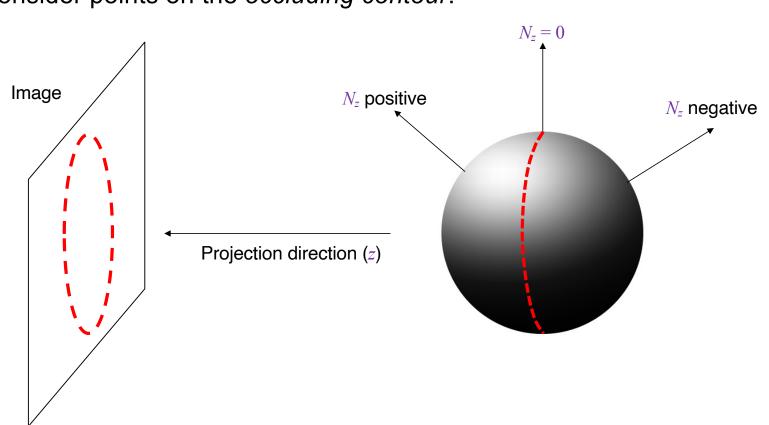
- Small taste of radiometry
- In-camera transformation of light
- Reflectance properties of surfaces
- Diffuse and specular reflection
- Shape from shading
- Estimating direction of light sources



- $I(x,y) = N(x,y) \cdot S(x,y)$
- Full 3D case:

 $\begin{bmatrix} N_x(x_1, y_1) & N_y(x_1, y_1) & N_z(x_1, y_1) \\ N_x(x_2, y_2) & N_y(x_2, y_2) & N_z(x_2, y_2) \\ \vdots & \vdots & \vdots \\ N_x(x_n, y_n) & N_y(x_n, y_n) & N_z(x_n, y_n) \end{bmatrix} \begin{bmatrix} S_x \\ S_y \\ S_z \end{bmatrix} = \begin{bmatrix} I(x_1, y_1) \\ I(x_2, y_2) \\ \vdots \\ I(x_n, y_n) \end{bmatrix}$ 

P. Nillius and J.-O. Eklundh. Automatic estimation of the projected light source direction. CVPR 2001

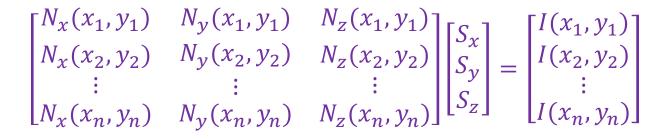


Consider points on the *occluding contour*:

P. Nillius and J.-O. Eklundh. Automatic estimation of the projected light source direction. CVPR 2001

N S  $I(x,y) = N(x,y) \cdot S(x,y)$ 

• Full 3D case:



• For points on the occluding contour  $(N_z = 0)$ :

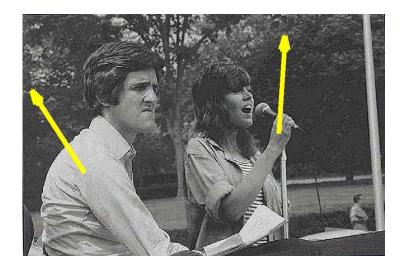
$N_x(x_1, y_1)$	$N_y(x_1, y_1)$		$[I(x_1, y_1)]$
$N_x(x_2, y_2)$	$N_y(x_2, y_2)$	$\begin{bmatrix} S_x \end{bmatrix} =$	$I(x_2, y_2)$
	$N_{y}(x_{1}, y_{1})$ $N_{y}(x_{2}, y_{2})$ $\vdots$ $N_{y}(x_{n}, y_{n})$	$[S_y]^-$	
$N_x(x_n, y_n)$	$N_y(x_n, y_n)$		$[I(x_n, y_n)]$

P. Nillius and J.-O. Eklundh. Automatic estimation of the projected light source direction. CVPR 2001



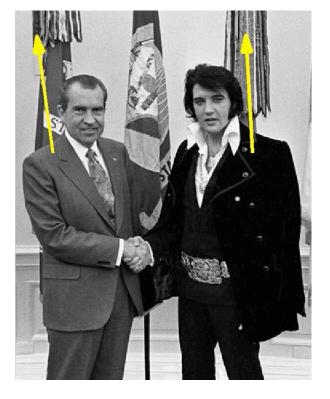
P. Nillius and J.-O. Eklundh. Automatic estimation of the projected light source direction. CVPR 2001

### Application: Detecting composite photos



Fake photo

Real photo



M. K. Johnson and H. Farid. Exposing Digital Forgeries by Detecting Inconsistencies in Lighting. ACM Multimedia and Security Workshop, 2005

### Bits and Pieces, Obstacles and Problems

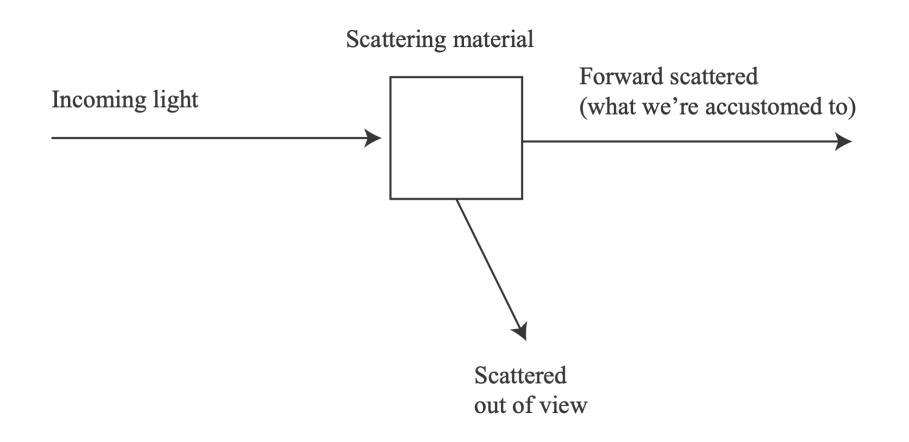
- Why does blueness reveal depth?
- What are the effects of interreflection?
- Does shading in a single image reveal shape?

#### Participating media

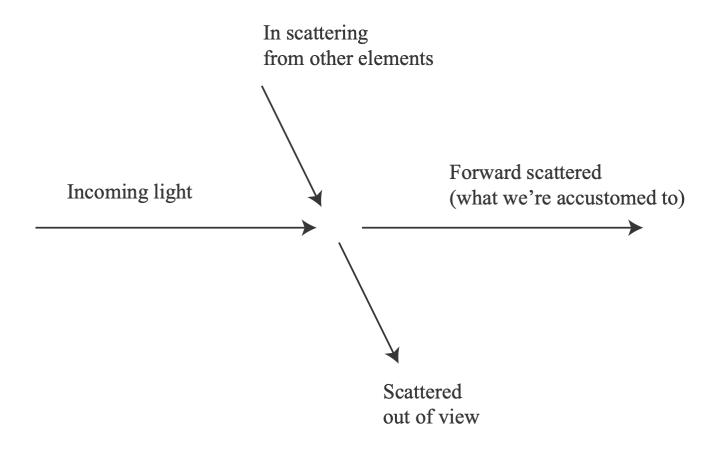
#### • for example,

- smoke,
- wet air (mist, fog)
- rain
- dusty air
- air at long scales
- Light leaves/enters a ray travelling through space
  - leaves because it is scattered out
  - enters because it is scattered in
- New visual effects

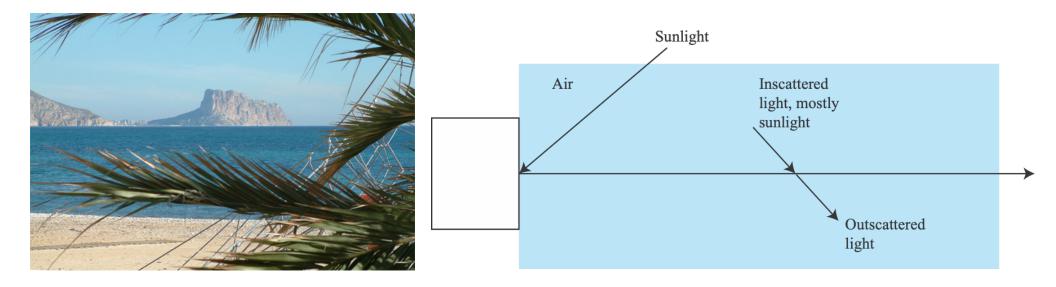
#### Light hits a small box of material

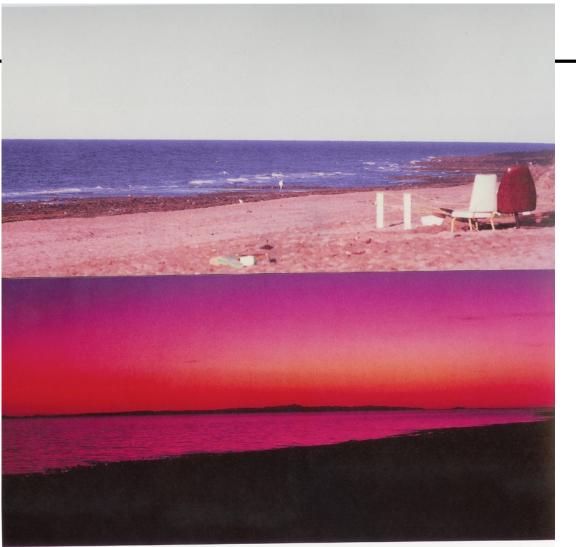


### A ray passing through scattering material



#### Airlight as a scattering effect



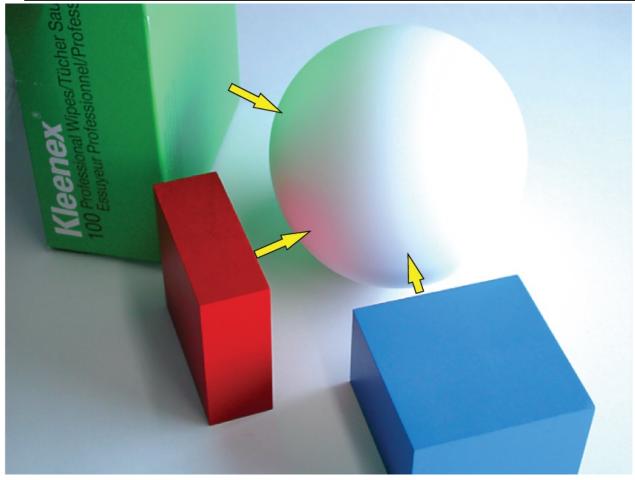


From Lynch and Livingstone, Color and Light in Nature



From Lynch and Livingstone, Color and Light in Nature

#### Interreflections



Odd fact: this does not seem to be a major problem for Photometric stereo

Q: why?

From Koenderink slides on image texture and the flow of light

#### Shape from shading

- Given a single shaded image of an object, recover:
  - Shape
  - Albedo
- People seem to be able to do this
- In Computer Vision:
  - Open since the early 70's
  - Mostly, still doesn't work
  - Mostly, attention has moved elsewhere

### Shading is an amazing single view cue

