

repa's

(13)

difficulty w/ CSG is its slow to render
(raytrace)

to a boundary or B-rep.

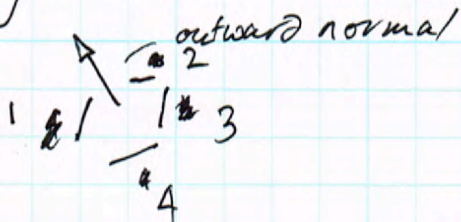
each primitive with a mesh of
tris.

typically represented with winged edge solid
of

- faces (faces) w/ ptrs to relevant edges, verts
- faces (edges)
- faces (vertices)

ventions

~~to list~~ list edges in CW order going around a face



edge rep as

first vert last vert left face right face

next, prev moving along left n.p along right

repr

least

rt . one incident edge .

rt all incident edges

repr

least

face one edge

face list of edges

the operations are straightforward

- rendering - throw faces into polygon renderer

- Some joins

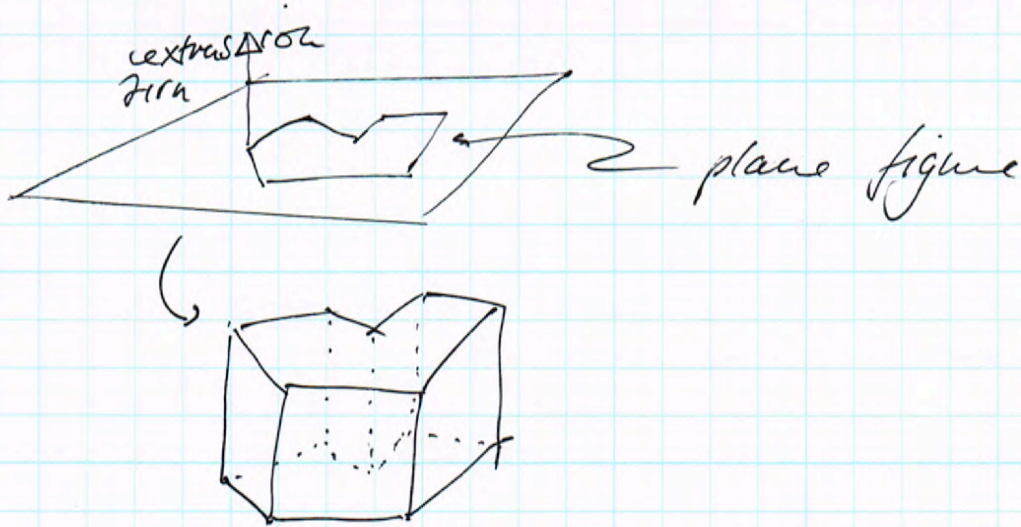
- eg. paste two objects together on shared face

cases:

- faces are "the same"
- not . . .

extrusion

- important operation to produce solids



- many objects are made like this.

section is relatively easy
 faces of Ω are pieces of faces
 of components.

convex components are particularly
 easy

- only one connected component
- ~~only one~~ no more than 1
 face of Ω from any face
 of component.
- verts are

(some of component verts) \cup

(\bullet face(A) \cap edge(B)) \cup
 some (face(B) \cap edge(A))

- each of these sets is easy
 to find.
- rest is pointer chasing (example)

~~sectioning WES is relatively straightforward~~

GHLY

~~find edge-face As, chase~~

pass from INES to general

group of polygons

sometimes w/ combinatorial structure

- note tough to have mesh if it isn't a solid.

UE not usually a solid

UE many computations can be tricky

UE hard to spot core geometric properties

UE • interpolation over meshes is easy

- ∴ normals are NOT piecewise const (or at least, not required to be)

WE MAKE ONE?

WES

elling system

h a set of sample points.

IG

meshes usually come from an assembly
 / surface patches

These are usually built w/

- splines
- subdivision surfs
- height maps (less often)

MAPS

-plest)

- have (x_i, y_i, z_i) ,
 scattered data.

(eg. image data)

interpolate or smooth, grid, resample

triangulate (x_i, y_i) use this to get mesh.

- Hard to avoid "bad" 3D triangles
- hard to sew together pieces
- resampling may bias.

|||

red Data interpolates, smoothers

have N pts (x_i, y_i, z_i)

'OT on grid

should like to build approximation
(interpolate)

strategy:

choose $\phi(x, y; x_i, y_i) = f((x-x_i)^2 + (y-y_i)^2)$
 (discuss choices later)

interpolate is

~~xxx~~

$$\sum_j a_j \phi(x, y; x_j, y_j)$$

$$z_i = \sum_j a_j \phi(x_i, y_i; x_j, y_j)$$

$$\underline{z} = M \underline{a}$$

light conditions on ϕ , M has full
 (Micchelli)

consider some choices of φ .

$$\varphi(x_i, y_i) = f((x-x_i)^2 + (y-y_i)^2)$$

$$= f(d^2)$$

$$\varphi(d^2) = \frac{1}{d^2 + \epsilon}$$

- ← • not finite support
- ϵ has important control properties

$$\varphi(d^2) = \max\left(1 - \left(\frac{d^2}{\sigma^2}\right), 0\right)$$

- ← • finite support
- σ has control properties

~~$$\varphi(d^2) = -\log(d^2 + \epsilon)$$~~

- ← • not finite support
- rather odd far away from data

- minimizes a form of bending cost

$$\left(\nabla^4 f = 0 \right)$$

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Note each of these basis fu's has a meter, which is essentially a scale u .

Choose $(x_u, y_u) \leftarrow$ random subset of points
 or random points
 base points

$$Z_i = \sum_{j \text{ base points}} a_j \phi(x_i, y_i; x_j, y_j) \|^2$$

$$\| \underline{z} - M_b \underline{a} \|^2$$

$$M_b^T \underline{a} = M_b^T \underline{z} \quad \text{— solve for } a$$

Choosing scale param: plot err vs scale
 for pt set, choose best

Number of base points:

- application logic
- MDL/AIC style reasoning

that choices of basis, scale
affect linear algebra.

$\begin{pmatrix} 1 & 2 \\ 2 & 0 \end{pmatrix}$ ← many zeros in M_6

← can often solve w/ iterative method

precondition

is often a good preconditioner.

minimizes Laplacian on some triangulation of
slits

point, pass to Shape from Shading ⁽²²⁾

1 form

Given shaded image of a surface,
with domain D , viewed orthographically,
with KNOWN RADIOMETRIC
LIBRATION, known albedo, known
use, RECOVER SURFACE GEOMETRY
(71).

Traditional Strategy:

$$I(x, y) = (N(x, y) \cdot S) \cdot \rho(x, y)$$

↑ image intensity, in radiometric units (hence calibration)

↑ unit normal

↑ source vector

↑ Known albedo

assume WHOG, $\rho = 1$

$$N(x, y) = \frac{(-h_x, -h_y, 1)}{(1 + h_x^2 + h_y^2)^{1/2}}$$

face $(x, y, h(x, y))$

PDE

$$+h_x^2 + h_y^2 + S_0 h_x + S_1 h_y - S_2 = 0$$

an instance of an eikonal eqn

• No soln when $I^2 > S_0^2 + S_1^2 + S_2^2$

can be shown that existence of solutions is a serious problem

generally, solving this PDE does not yield approaches that

- make sense mathematically
- make sense practically
- yield good looking solns

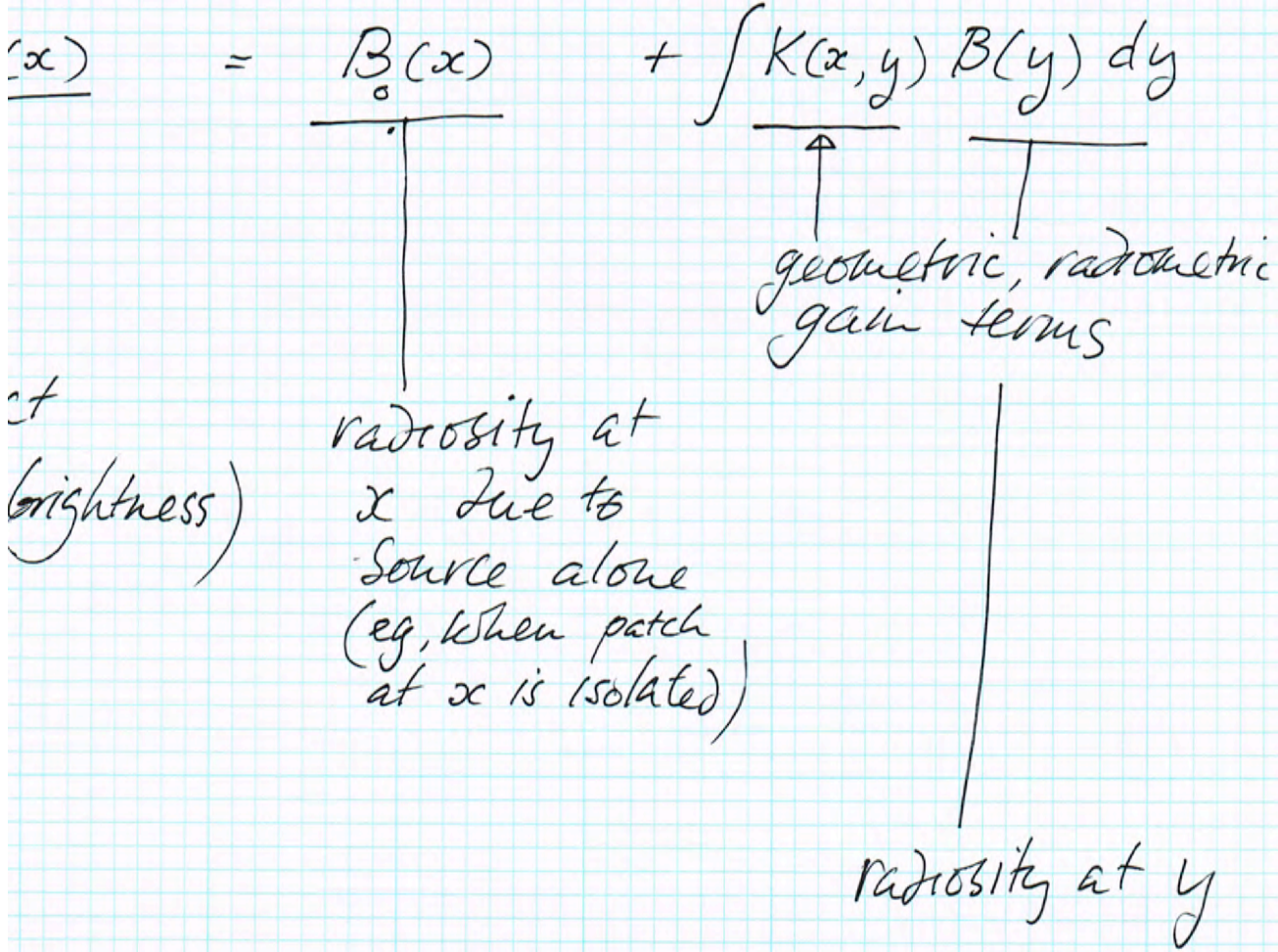
tric model is WRONG

correct for

- diffuse surfaces
- isolated patches
- distant sources

but these conditions don't apply.

radiometric model is, at least



at (brightness)

rel is wildly unpromising

if pairs of patches interact

then patches change interaction

y_2



→ x light transfer occurs

→ x doesn't, z is in the way

a complicated fn of geometry

there are claims in literature that can work ~~the~~ interrefl's into shape hence — I discount them.

Modify shading model to

$$I(x, y) = G(N; S)$$

↑ some fn of the unit normal

natural G

$$G(N; S) = \sum_i a_i S_i(N)$$

↑ spherical harmonics
↑ encode source properties

yields another PDE

• still have existence problems

pts to lack existence problems of variational methods ~~just~~ haven't ed.

+ Malik

(27)

minimize $\left[\text{Cost}(\text{surface}, \text{albedo}, \text{illum}) \right]$

subject to

$$I - \rho G(N; a) = 0$$

Does not have existence problems,
I is badly mishandled.

What is $\text{Cost}(\text{surface}, \text{albedo}, \text{illum})$?

(+ should it be)

assumes:

- illum field is "smooth" except at shadows
- albedo field is $> 0, < 1$, has few slow changes, has few distinct values

Surface is "smooth"

- turns away from eye at outline
- is biased toward front
- ~~is~~ tends to be locally "flat"

1. $\frac{\partial}{\partial x} h_x^2 + h_y^2 \geq \text{thresh (at boundary)}$