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# Sem Definite programming,

or how to solve R.

SDP:

$$\text{Min } C^T x$$

$$\text{s.t. } F(x) \succeq 0$$

↳ is positive Sem Definite

and  $F(x) = F_0 + \sum_i x_i F_i$

↑ symmetric matrices

• this problem is convex

(obvious that objective is convex)

Domain is convex because

$$F_\alpha \succeq 0, F_\beta \succeq 0$$

$$\Rightarrow t F_\alpha + (1-t) F_\beta \succeq 0$$

$$t \in [0, 1]$$

Cases :

• Linear program:

$$\min c^T x$$

$$\text{st } Ax + b \geq 0$$

↑ component wise inequality

$$\text{now } \text{diag}(v) \geq 0 \Leftrightarrow v \geq 0$$

$$\therefore Ax + b \geq 0 \Leftrightarrow \text{diag}[Ax + b] \geq 0$$

$$\text{diag } A = [a_1 \dots a_n]$$

↑ cols

$$\text{diag}[Ax + b] = \text{diag}(b) + \sum_i x_i \text{diag}(a_i)$$

$$\text{so } \min c^T x$$

$$\text{st } \text{diag}(b) + \sum_i x_i \text{diag}(a_i) \geq 0$$

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A problem that is an SDP but not an LP

$$\textcircled{\text{I}} \quad \min \frac{(c^T x)^2}{d^T x}$$

$$\text{st} \quad Ax + b \geq 0$$

(where  $d^T x > 0$  for  $x$  st.  $Ax + b \geq 0$ )

this is convex, Not LP.

$$\textcircled{\text{II}} \quad \min \quad t$$

$$\text{st} \quad Ax + b \geq 0$$

$$\frac{(c^T x)^2}{(d^T x)} \leq t$$

I  $\equiv$  II Trick :

$$\begin{bmatrix} t & (c^T x) \\ (c^T x) & (d^T x) \end{bmatrix} \succeq 0$$

is:  $t(d^T x) - (c^T x)^2 \geq 0$

but  $d^T x > 0$  by assumption, so  $t - \frac{(c^T x)^2}{d^T x} \geq 0$

so

min t

III

$$st \begin{bmatrix} \text{diag}(Ax + b) & 0 & 0 \\ 0 & t & (c^T x) \\ 0 & (c^T x) & (d^T x) \end{bmatrix} \succeq 0$$

is equivalent to I; but III is an SDP.

Fact: SDP's can be solved fairly efficiently with interior point methods (estimates later).

Further examples:

Quadratically constrained Quadratic program

# Schur Complements

consider

$$X = \begin{bmatrix} A & B \\ B^T & C \end{bmatrix}$$

A, C, Symmetric

and assume A positive definite

now

$$X \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} u \\ v \end{bmatrix}$$

$$Ax + By = u$$

$$B^T x + Cy = v$$

So:  $x = A^{-1}u - A^{-1}By$

and  $B^T A^{-1}u - B^T A^{-1}By + Cy = v$

write  $S = C - B^T A^{-1}B$

$$B^T A^{-1}u + Sy = v$$

$$y = S^{-1}(v - B^T A^{-1}u)$$

S is very interesting, w/ applications to positive definiteness.

consider

$$\min_u [u^T A u + 2v^T B^T u + v^T C v]$$

(for fixed v)

then  $u = -A^{-1} B v$  so the value is

$$\begin{aligned} & v^T B^T A^{-1} A A^{-1} B v - 2v^T B^T A^{-1} B v + v^T C v \\ &= v^T S v \end{aligned}$$

this gives

$X \succ 0 \iff A \succ 0, S \succ 0$
$A \succ 0 \implies [X \succ 0 \iff S \succ 0]$

worth remembering!

SDP example: Quadratically constrained QP.

assume convex quadratic constraints

$$(Ax + b)^T (Ax + b) - c^T x - d \leq 0$$

By Schur complement equiv to

$$\begin{bmatrix} I & Ax + b \\ (Ax + b)^T & c^T x + d \end{bmatrix} \preceq 0$$

↳ this has right form!

so it we have

$$\text{minimize } (A_0 x + b_0)^T (A_0 x + b_0) - c_0^T x - d_0$$

st.

$$(A_i x + b_i)^T (A_i x + b_i) - c_i^T x - d_i \leq 0$$

we can rearrange to get

min t

subject to

$$\begin{bmatrix}
 \text{OF block} & 0 & 0 & 0 & \dots \\
 0 & C_1 \text{ block} & 0 & & \\
 0 & 0 & C_2 \text{ block} & & \\
 \vdots & \vdots & & \ddots & \\
 \vdots & \vdots & & & \ddots
 \end{bmatrix} \succeq 0$$

where

$$C_i \text{ block} = \begin{bmatrix} I & A_i x + b_i \\ (A_i x + b_i)^T & c_i x + d_i \end{bmatrix}$$

$$C_0 \text{ OF block} = \begin{bmatrix} I & A_0 x + b_0 \\ (A_0 x + b_0)^T & c_0 x + d_0 + t \end{bmatrix}$$