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Constrained optimization:

$$\begin{aligned} \min f(x) \quad \text{st} \quad & c_i(x) = 0 \\ & g_i(x) \geq 0 \end{aligned}$$

Lagrangian

$$\mathcal{L}(x, \lambda) = f(x) - \lambda^{(e)T} c - \lambda^{(i)T} g$$

(here λ is a vector of constraints whose elements are ~~csp~~ ~~ineq~~ $\lambda^{(i)}$ or eq constraints $\lambda^{(e)}$)

Necessary conditions (KKT cond)

$$\begin{aligned} \nabla_x \mathcal{L} &= 0 & g_i(x) &\geq 0 \\ c_i(x) &= 0 & \lambda^{(i)} &\geq 0 \\ \lambda^{(e)} c_i &= 0 & \lambda^{(i)} g_i &= 0 \end{aligned}$$

- Assume equality inequality constraints only.

$$\min f(x) \quad \text{s.t.} \quad g_i(x) \geq 0$$

example:

- Assume $\min - \frac{a^T x}{\|x\|_2}$ is strongly convex = 6

$$\begin{aligned} \mathcal{L}(x, \lambda) &= x^T x - \lambda^T (Ax - b) \\ \mathcal{L}(x, \lambda) &= \frac{f^T(x)}{\|x\|_2} - \lambda^T g(x) \end{aligned}$$

from first condition: define dual objective q to be

$$x^T - \lambda^T A = 0$$

$$i.e. q(\lambda) = \bar{x} = \max_x \mathcal{L}(x, \lambda)$$

substitute on domain τ such that $q(\lambda) > -\infty$

$$\lambda^T \frac{AA^T \lambda}{2} - \lambda^T (AA^T \lambda - b)$$

dual problem:

Knowledge of λ w/ $q(\lambda)$ values is $\lambda \geq 0$
powerful!

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Thm: q is concave, domain is convex
(straight forward)

Thm: for feasible x , any λ

$$q(\lambda) \leq f(x)$$

(straight forward)

Thm: suppose x is soln of primal, f and $-g_i$ are convex; then λ such that (x, λ) satisfies KKT is a soln of dual

~~Thm~~: ~~with~~ other way round requires stronger technical condns

Thm: value of dual \leq value of primal.

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Common application: in important cases, one may be able to write the dual directly.

SVM

$$\begin{array}{l} \min \quad \frac{w'w}{2} \\ \text{st } y_i (w'x_i + b) \geq 1 \end{array} \quad \left. \vphantom{\begin{array}{l} \min \\ \text{st} \end{array}} \right\} \begin{array}{l} \text{Primal form,} \\ \text{Separable} \end{array}$$

$$\mathcal{L}(w, \lambda) = \frac{w'w}{2} - \sum_i \lambda_i \{ [y_i (w'x_i + b)] - 1 \}$$

$$\nabla_w \mathcal{L} = 0 = w - \sum_i \lambda_i \{ [y_i x_i] \}$$

$$\nabla_b \mathcal{L} = 0 = - \sum_i \lambda_i y_i$$

Subst :

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Subst

$$\mathcal{L}_D = \sum_i \lambda_i - \frac{1}{2} \sum_{ij} \lambda_i \lambda_j [y_i y_j (x_i^T x_j)]$$

Notice constraints

$$\sum_i \lambda_i y_i = 0$$

$$\lambda_i \geq 0$$

and we must max this in λ

If there is an fp for primal, the
max is soln to primal

i.e. Value(Dual) = Value(Primal)

What if data is not separable? (7)

$$\begin{array}{l} \text{min } \frac{\omega' \omega}{2} + C \sum_i \xi_i \\ \text{st } y_i (\omega' x_i + b) \geq 1 - \xi_i \\ \xi_i \geq 0 \end{array} \quad \left. \vphantom{\begin{array}{l} \text{min } \frac{\omega' \omega}{2} + C \sum_i \xi_i \\ \text{st } y_i (\omega' x_i + b) \geq 1 - \xi_i \\ \xi_i \geq 0 \end{array}} \right\} \text{Primal prob}$$

ξ_i are slack variables

$$\mathcal{L}_p = \frac{\omega' \omega}{2} + C \sum_i \xi_i - \sum_i \lambda_i [y_i (\omega' x_i + b) - 1 + \xi_i] - \sum_i \mu_i \xi_i$$

$$\nabla_{\omega} \mathcal{L}_p = \omega - \sum_i \lambda_i y_i x_i = 0$$

$$\nabla_b \mathcal{L}_p = 0 = -\sum_i \lambda_i y_i$$

$$\nabla_{\xi_i} \mathcal{L}_p = C - \lambda_i - \mu_i = 0 \quad \left. \vphantom{\nabla_{\xi_i} \mathcal{L}_p} \right\} \rightarrow \text{this gets rid of } \xi_i$$

So
Next we have



$$L_D = \sum_i \lambda_i - \frac{1}{2} \sum_{i,j} y_i y_j \lambda_i \lambda_j x_i' x_j$$

subject to

$$\sum_i \lambda_i y_i = 0$$

$$0 \leq \lambda_i \leq C$$

Notice that ξ_i can be interpreted
as a loss

$$\text{hinge loss} \left(\frac{y_i y_p}{2, 1, 1} \right) = \max(0, 1 - y_i y_p)$$

Methods :

Quadratic penalty method

(assume equalities)

$$\min_x f(x) + \frac{\mu}{2} \sum_i c_i^2(x) = Q_\mu(x)$$

and drive $\mu \rightarrow \infty$, resolve

Notice at soln

$$\nabla_x Q_\mu = 0 = \nabla f + \sum_i (\mu c_i(x_*) \nabla c_i(x))$$

By inspection, this would match

$$\nabla_x \mathcal{L} = 0, \text{ if}$$

$$-\mu c_i = \lambda_i^*$$

Which suggests that at conv $c_i = \frac{-\lambda_i^*}{\mu}$

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This looks OK, because $\mu_k \rightarrow \infty$, but
not exact. Also $\mu_k \rightarrow \infty$ creates
major probs w/ Hessian

Augmented Lagrangian method

consider

$$\mathcal{L}_A(x, \lambda; \mu) = f - \sum_i \lambda_i c_i + \frac{\mu}{2} \sum_i c_i^2$$

- have an est of λ^k, μ_k , get x^*
- at x^* $\nabla_{x^*} \mathcal{L}_A = 0 = \nabla f - \sum_i (\lambda_i^k - \mu_k c_i) \nabla c_i$
- This suggests $\lambda_i^* \approx (\lambda_i^k - \mu_k c_i)$
and $c_i \approx -\frac{1}{\mu_k} [\lambda_i^* - \lambda_i^k]$
which suggests moving $\lambda_i \rightarrow \lambda_i^*$

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But we have a good est:

$$\lambda_i^* \approx (\lambda_i^k - \mu_k c_i)$$

so update ests, go again.

1) Method converges w/o increasing μ_k indefinitely